

**Important Instructions to examiners:**

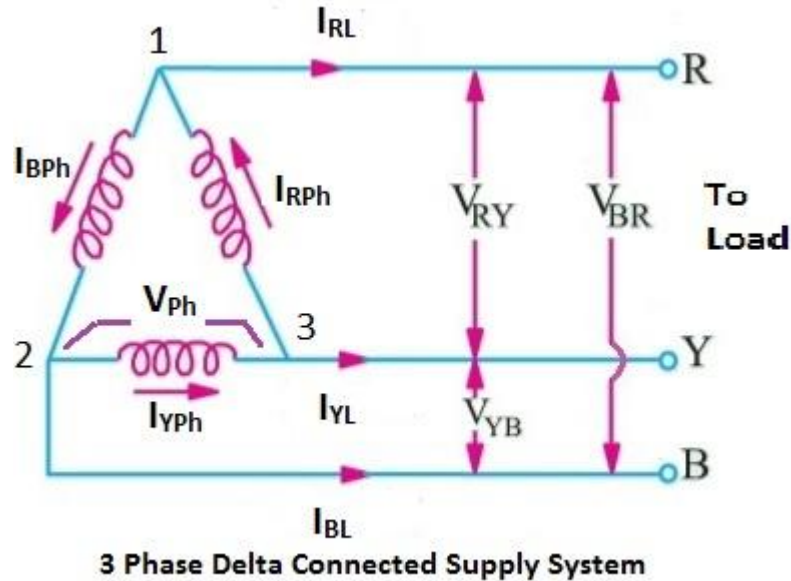
- 1) The answers should be examined by key words and not as word-to-word as given in the model answer scheme.
- 2) The model answer and the answer written by candidate may vary but the examiner may try to assess the understanding level of the candidate.
- 3) The language errors such as grammatical, spelling errors should not be given more Importance (Not applicable for subject English and Communication Skills).
- 4) While assessing figures, examiner may give credit for principal components indicated in the figure. The figures drawn by candidate and model answer may vary. The examiner may give credit for any equivalent figure drawn.
- 5) Credits may be given step wise for numerical problems. In some cases, the assumed constant values may vary and there may be some difference in the candidate's answers and model answer.
- 6) In case of some questions credit may be given by judgement on part of examiner of relevant answer based on candidate's understanding.
- 7) For programming language papers, credit may be given to any other program based on equivalent concept.

Q. No	Detailed Solution	MARKS Distribution
1	Attempt any TEN of the following	
1.a	List the stages of electrical power system i)Generation ii)Transmission iii)Distribution	For (i) and (ii) 1M For (iii) 1M
1.b	State working principle of PMMC type meters When a current carrying moving coil is placed in a magnetic field, a force is experienced on it and it is proportional to value of current flowing through it.	1M
1.c	State the applications of wattmeter and state the unit of power i) Applications of wattmeter:- To measure active power in DC and AC circuit ii) Unit of power:- Watt	1M 1M
1.d	List the main parts of DC machine	



	i)Stator parts:- 1)Yoke 2)Pole 3)Field coils	1M
	ii)Rotor parts:- 1)Armature 2) Commutator 3)Brushes	1M
1.e	Define the terms:- i)Transformation ratio ii)Voltage ratio	
	i) Transformation ratio:- It is defined as the ratio of the secondary winding turns to the primary winding turns of a transformer.	1M
	ii) Voltage ratio:- It is defined as the ratio of the secondary winding voltage to the primary winding voltage of a transformer.	1M
1.f	State the emf equation of a transformer	
	$E = 4.44 f N \phi_m$ volt	1M
	Where	
	E= Induced emf in winding	1M
	f = Frequency of AC supply source	
	N = Number of turns of winding	
	ϕ_m = Maximum value of magnetic flux linking with winding	
1.g	Define slip and write the formula to determine percentage slip.	
	i)Slip:- It is the ratio of relative speed of rotor (difference between synchronous speed and rotor speed) to the synchronous speed of rotating magnetic field of stator.	1M
	ii)Percentage slip = $(NS - N) / NS * 100$	
	where	
	NS = synchronous speed of rotating magnetic field of stator	
	N = speed of rotor	1M
1.h	What is the function of MCCB and fuse	
	i)MCCB:- It provide over current and short circuit protection (fault interruption function)in a power circuit with capacity up to 3KA and can also be used as a switch under normal working condition.	1M
	ii)Fuse:- It provide protection against over current and short circuits.	

i) Delta connected 3-phase supply system diagram:-



ii) Marking of line voltage and phase voltage, line current and phase current.

Line Current = I_{RL} , I_{YL} , I_{BL}

Phase Current = I_{RPh} , I_{YPh} , I_{BPh}

Line Voltage = V_{RY} , V_{YB} , V_{BR}

Phase Voltage = V_{Ph} (Voltage across terminal 1-2, 2-3, 3-1)

iii) Power equation:-

$$\text{Power}(P) = \sqrt{3} V_L I_L \cos\phi \quad \text{Watt}$$

Where,

V_L = Line voltage in volt

I_L = Line current in ampere

$\cos\phi$ = Power factor of load

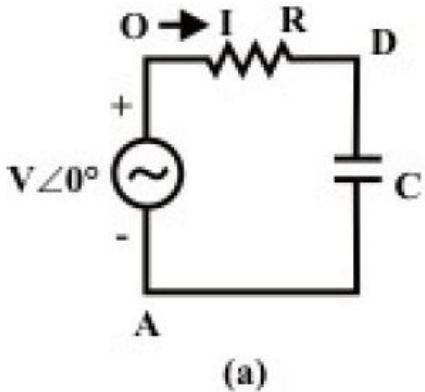


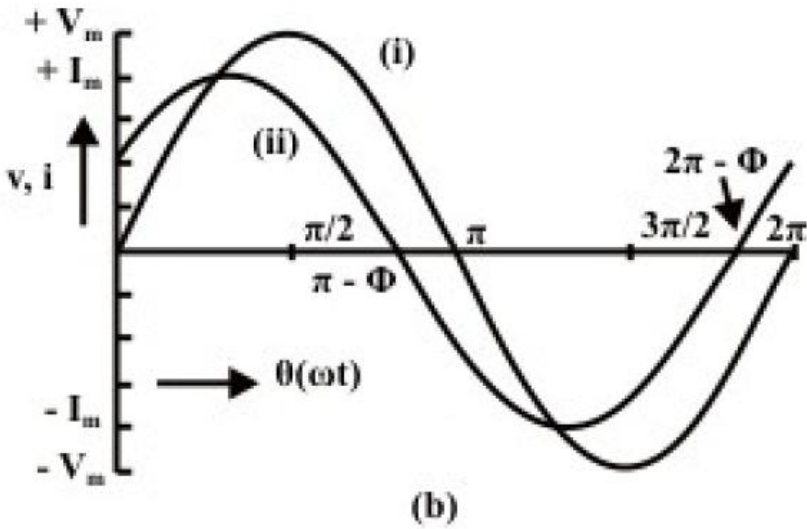
	<p>$I_{Ph} = 23.094$ Ampere</p> <p>ii) Line current(I_L):-</p> <p>$I_L = I_{Ph}$</p> <p>$I_L = 23.094$ Ampere</p> <p>iii) Power factor($\cos\phi$):</p> <p>As the circuit has no inductance or capacitance, it is pure resistive circuit. Hence $Z=R=10$ ohm</p> <p>$\cos\phi = R/Z=10/10=1.0$</p> <p>Power factor=1.0</p> <p>iv) Power consumed(P):-</p> <p>$P = \sqrt{3} V_L I_L \cos\phi$ Watt</p> <p>$P = \sqrt{3} *400*23.094*1.0$</p> <p>$P = 16000$ watt</p>	<p>1/2M</p> <p>1/2M</p> <p>1/2M</p> <p>1/2M</p> <p>1/2M</p> <p>1/2M</p> <p>1/2M</p>
2.f	<p>Draw a neat labelled diagram of single phase energy meter showing all its important parts.</p> <p>i) Diagram:-</p> <p>ii) Labelling:- VC= Voltage/ Pressure Coil</p> <p>PFC= Power Factor Compensator</p> <p>FC1 ,FC2 = Friction Compensator</p> <p>CC = Current Coil</p>	<p>3M</p> <p>1M</p>

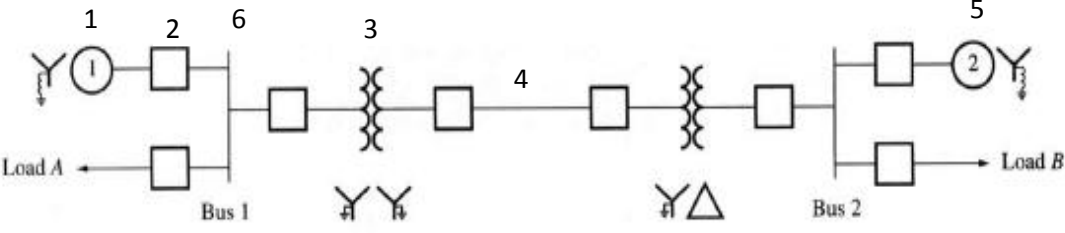
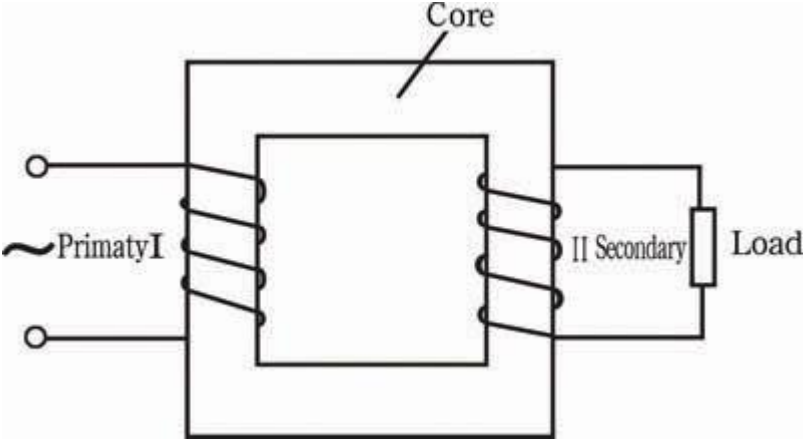
	<p style="text-align: center;">Single phase induction type energy meter</p>	
<p>Q-3</p>	<p>Attempt any FOUR of the following:</p>	<p>Marks (16)</p>
	<p>a) Draw the schematic diagram of dc compound (long shunt) motor (04)</p> <p><u>Diagram:</u></p> <p><u>Labeling:</u></p> <p>Rsc – Series field winding</p> <p>Rsh – Shunt field winding</p> <p>E or V – Applied voltage volt</p> <p>Ra- Armature resistance</p>	<p>02 Mark</p> <p>02 Mark</p>

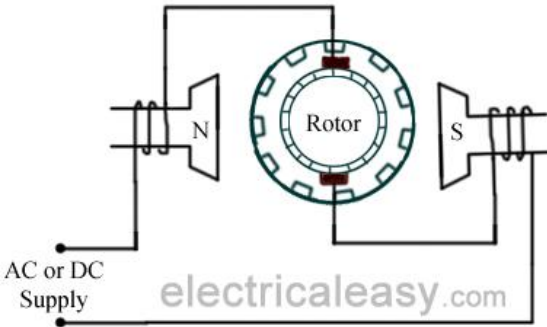


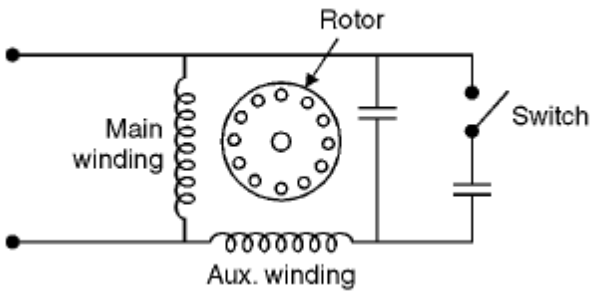
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	= 1200 Volt	
	<p>c) Compare auto transformer with a two winding transformer on the basis of construction, efficiency, size, applications.</p> <p>Auto transformer</p> <ol style="list-style-type: none">1) It has a single wing for input and output and these are electrical connected2) Autotransformer copper loss in the common portion of the winding will be less, so efficiency will be slightly more3) The autotransformer is lesser size than ordinary two winding transformer for the same rating4) It is used in laboratory for variable supply and also used as starter <p>Two winding transformer</p> <ol style="list-style-type: none">1) Two winding transformer has two separate magnetically coupled coils with no electrical connection between them.2) As it has two separate winding so copper loss is more hence efficiency will be less.3) Two winding transformer is bigger in size than autotransformer for the same rating4) It is used in power system to step up or step down the voltage level	(04) Each point has 1 mark 1x4= 04
	<p>d) Draw and explain circuit diagram of R-C circuit</p> <p><u>Circuit diagram</u></p>  <p>(a)</p>	(04) 01 Mark

	<p><u>Wave form</u></p>  <p><u>Explanation:</u></p> <p>In a series circuit, the current is the same through both the resistor and the capacitor. The resistor voltage is in phase with the current, and the capacitor voltage lags the current by 90°.</p> <p>The impedance of a series RC circuit is determined by both the resistance (R) and the capacitive reactance (XC) ($Z = R - jXC$)</p> $= R - jX_C = R - j\frac{1}{\omega C}$ <p>Note that the current leads the voltage by the angle ϕ, value as given above. In this case, the voltage phasor has been taken as reference phase, with the current phasor leading the voltage phasor by the angle, ϕ. This can be observed from diagram of waveforms. The power factor in this circuit is less than 1 (one), power is only consumed in the resistance, R, but not in the capacitance.</p>	<p>01 Mark</p> <p>02 Mark</p>
	<p>e) Draw a single line diagram of electrical power system and label it.</p> <p><u>Diagram</u></p>	<p>(04)</p>

	 <p>Labeling:</p> <p>1 & 5 – Generators</p> <p>2- Circuit Breaker</p> <p>3- Transformer</p> <p>4- Transmission line</p> <p>6- Bus bar</p>	<p>Diagram 02 marks</p> <p>02 Marks</p>
<p>f) Explain the working principle of transformer and draw a neat labeled diagram of the same.</p> <p><u>Working Principle</u></p> <p>The working principle of transformer is depends upon Faraday's law of electromagnetic induction. Actually, mutual induction between two or more winding is responsible for transformation action in an electrical transformer.</p> <p>According to these Faraday's laws, "Rate of change of flux linkage with respect to time is directly proportional to the induced EMF in a conductor or coil".</p>		<p>(04)</p> <p>02 Mark</p> <p>01 Mark</p>

	<p>1 cycle of the alternating flux is the periodic time T, where</p> $T = (1/f) \text{ seconds}$ <p>The flux rises sinusoidally from zero to its maximum value in (1/4) cycle, and the time for (1/4) cycle is (1/4x f) seconds. Hence the average rate of change of flux = $(\phi_m / (1/4 \times f))$ $4 \times f \times \phi_m$ Wb/s, and since 1 Wb/s = 1 volt, the average e.m.f. induced in each turn = $4 \times f \times \phi_m$ volts. As the flux ϕ varies sinusoidally, then a sinusoidal e.m.f. will be induced in each turn of both primary and secondary windings.</p> <p>For a sine wave,</p> $\text{Form factor} = \text{r.m.s. value} / \text{average value}$ $= 1.11$ <p>Hence r.m.s. value = form factor x average value = 1.11 x average value Thus r.m.s. e.m.f. induced in each turn</p> $= 1.11 \times 4f \phi_m \text{ volts}$ $= 4.44 f \phi_m \text{ volts}$ <p>Therefore, r.m.s. value of e.m.f. induced in primary and secondary winding,</p> $E_1 = 4.44 f \phi_m N_1 \text{ volts}$ $E_2 = 4.44 f \phi_m N_2 \text{ volts}$	<p>01</p> <p>01</p>
	<p>b) Explain the working principle of universal motor and state its two applications</p> <p>Circuit diagram:</p> 	<p>01 mar k</p>

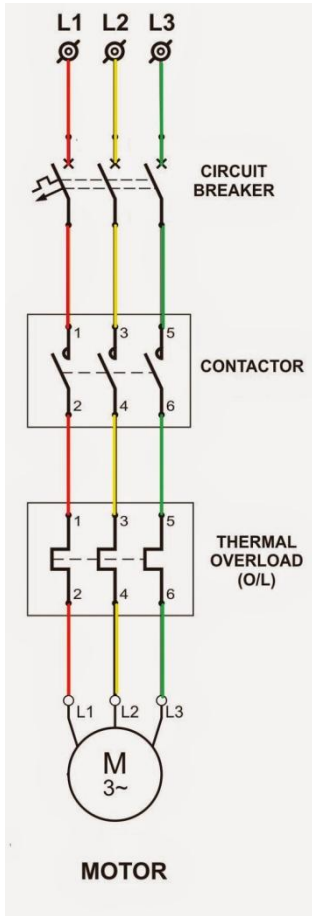
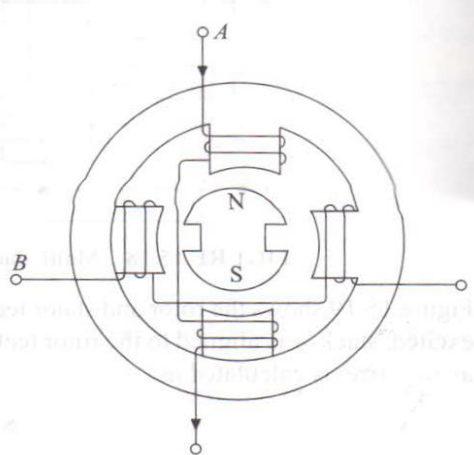
	<p>Working principle:</p> <p>A universal motor works on either DC or single phase AC supply. When the universal motor is fed with a DC supply, it works as a DC series motor. When current flows in the field winding, it produces an electromagnetic field. The same current also flows from the armature conductors. When a current carrying conductor is placed in an electromagnetic field, it experiences a mechanical force. Due to this mechanical force, or torque, the rotor starts to rotate. The direction of this force is given by <u>Fleming's left hand rule</u>.</p> <p>The universal motors applications are</p> <ol style="list-style-type: none"> 1) portable drills 2) hair dryers 3) grinders 4) table-fans 5) blowers 6) polishers 7) Kitchen appliances 	<p>02 Mar k</p> <p>Any two</p> <p>App l.</p> <p>01 Mar k</p>
	<p>c) Draw a neat diagram and explain working of capacitor start capacitor run single phase I.M.</p> <p>Circuit Diagram:</p>  <p>Working:</p> <p>In this type of motor two capacitors are used with the auxiliary winding as shown in above diagram, one for starting and other during start and run, the starting and running performances are achieved are good. The small value capacitor are required for optimum running condition it is permanently connected in running winding and high value capacitor</p>	<p>Dia gra m</p> <p>02 mar ks</p> <p>02 mar ks</p>

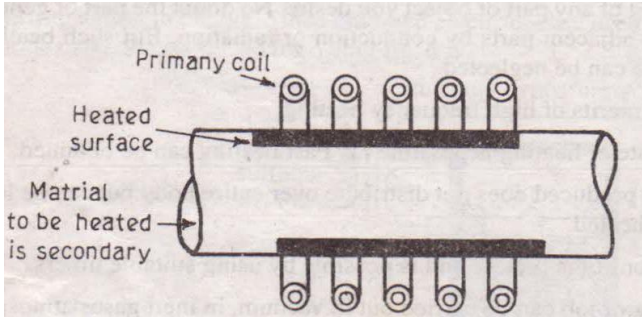


	<p>is connected parallel.</p> <p>This motor has two winding one is main winding and other is starting winding and both are displaced by the 90 degree electrical. When the single phase supply is applied to the winding the current through main winding and starting or running winding these currents are not exactly 90 degree apart. The permanent capacitor make these currents near about 90 degree. Due to the field interaction of these two winding torque is developed. When motor start then one low value capacitor get disconnect from circuit.</p>	
	<p>d) Explain any four factors to be considered while selecting a motor for a particular applications</p> <p>The factors considered while selections of motors are</p> <ol style="list-style-type: none">1) Nature of the load : The load on the motor may be constant or variable according to the nature of load the motor selected for constant torque or variable torque2) Speed Requirement: The application may required constant speed or variable speed according to this motor of constant speed or variable speed motor is selected.3) Environmental condition: The plant condition means in chemical plant environment is explosive and hence the totally enclosed type motor is selected4) Efficiency : In some application precise output required in that case high efficient motors are used.5) Price : cost is one of the factor which consider in motor selection6) Motor Duty Cycle: Some applications motor required for continuous operation and hence duty cycle of motor is also taken in to account in selection.7) Temperature Ratings: It is important to use a consistent measure to compare the efficiency of one motor to another.	(04) Any for fact or each of 1 marks 1x4 =04
	<p>e) A 3-phase , 4-pole, 50 Hz, IM works with a full load slip of 3 % Find:</p> <ol style="list-style-type: none">i) Synchronous speedii) Actual speed of motor <p>Solution:</p> <p>Synchronous speed $N_s = 120 f/p$</p> <p>Where f -frequency</p> <p>p- No of poles</p> <p>$N_s = 120 \times 50/4 = 1500 \text{ rpm}$</p>	(04) 01 mark 01 marks

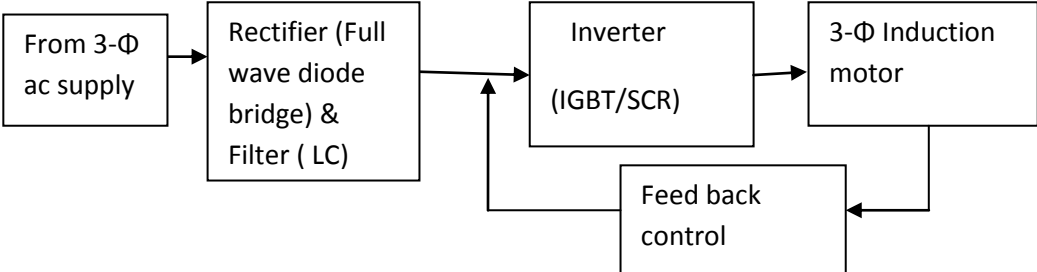


	<p>$Slip = s = (N_s - N_r) / N_s = 1 - N_r / N_s$</p> <p>$N_s$- Synchronous speed</p> <p>N_r- Rotor or actual speed</p> <p>$N_r = (1 - s) N_s$</p> <p>$N_r = (1 - 0.03) \times 1500$</p> <p>$= 1455 \text{ rpm}$</p>	01 Mar ks 01 Mar ks
	<p>f) State the types of an alternator. Which type of rotor is suitable for slow speed diesel engines? state reasons</p> <p>Types of alternator are as follows</p> <p>1) Alternators are classified according to type of field system</p> <p>Stationary field system type</p> <p>Rotating field system type</p> <p>2) Alternators can be classified into the following two types according to its rotor construction(shape of field system)</p> <p>Smooth cylindrical type alternator</p> <p>Salient pole alternator</p> <p>Salient pole alternator is suitable for slow/ low speed operation.</p> <p>As the speed of operation is low , salient pole type synchronous generators/ alternator are used because these allow better ventilation and also have other advantages over smooth cylindrical type rotor</p>	(04) 01 Mar k 01 Mar k 01 Mar k 01 Mar k

<p>Q.5 a)</p>	<p style="text-align: center;">Direct on Line starter for 3-phase induction Motor</p>  <p style="text-align: center;">Circuit diagram for DOL starter for 3-phase induction motor</p>	<p>4M Labe 1 01 M Dig. 03 M</p>
<p>5 b)</p>	<p>Working principle of Permanent type stepper Motor:</p> 	<p>Dia 1M</p>

	<p style="text-align: center;">Two pole permanent magnet stepper motor</p> <p>-Operating principle of such motor is understand with the help of above diagram, where the rotor has two poles and stator has four poles. Since two stator poles are energized by one winding, the motor has two windings or phases marked as A and B.</p> <p>-When phase A is excited ,the rotor will aligned as shown in fig depends upon flux formation of stator ,here upper part of stator will be S pole and bottom part will be N pole.</p> <p>-If excitation is switched to phase B , the rotor will be moved by 90^0 where as the direction will be decided by the winding polarity and current direction. Here in clock wise direction.</p>	3M
5-c)	<p>Induction Heating</p> <div style="text-align: center;">  <p>Diagram of Induction Heating</p> </div> <p>Principle:</p> <p>-Induction heating is based upon the principle of current induced in the conducting material due to electromagnetic induction action which is similar to transformer action.</p> <p>-Consider a coil surrounding the conducting material to be heated i.e. charge as shown in the fig . The alternating current will set up flux in charge ,its value depends upon permeability of conducting material. This alternating flux as per Lenz’s law will produce the current in the charge which is in opposite direction to the flow of current in the coil.</p> <p>-Coil act as primary and charge act as a secondary of transformer. The current induced in the Charge (secondary) is due to induction effect. The induced current in the charge produces heat proportional to i^2R ,where i is the induced current and R is resistance of the charge .This developed heat is useful for heating the charge. Since this heating is due to induced current in charge, it is called induction heating.</p>	Dig. 1M 3M
5 d)	<p>Speed control of 3-phase induction motor by VFD:</p> <p>VFD is a power electronics based device which converts a basic fixed frequency ,fixed voltage sine wave power to a variable frequency ,variable output voltage used to control speed of induction motor. It regulates the speed of three phase induction motor by controlling the frequency and voltage of power supplied to the motor.</p>	



	<p>As $N_s = \frac{120f}{p}$ since the no of pole is constant the speed N_s can be varied by continuously changing the frequency.</p> <p>It consist of three stages to control a 3 phase induction motor:</p> <p>(As shown in following Block diagram)</p> <ol style="list-style-type: none"> i) Rectifier and filter stage- A full wave power based solid state rectifier converts 3 phase 50 Hz power from a standard 220V,440V to adjustable DC voltage. The system may include transformer for high voltage system. To get pure d.c. filters are used. ii) Inverter stage- Power electronics switches such as IGBT,SCR switch the DC power from rectifier ON and OFF to produce a current or voltage waveform at the required new frequency. Now days, PWM technique is also used because the current and voltage waveform at output in this technique is approximately sine wave. In above given electronics switches, Output frequency is adjusted by changing the no of pulses per half cycle or by varying the period of time cycle. Output voltage is varied by varying the gain of inverter. iii) Control System: Its function is to control output voltage of inverter to maintain constant ratio of voltage to frequency(V/f).It consist of an electronic circuit which receives the feedback information from the driven motor and adjust the output voltage or frequency to the desired values. <p>Block Diagram of VFD:</p>  <pre> graph LR A[From 3-Φ ac supply] --> B[Rectifier (Full wave diode bridge) & Filter (LC)] B --> C[Inverter (IGBT/SCR)] C --> D[3-Φ Induction motor] D --> E[Feed back control] E --> C </pre>	<p>1M</p> <p>1M</p> <p>1M</p> <p>1M</p>
<p>5 e)</p>	<p>Electric drives are preferred over Mechanical drives since</p> <ol style="list-style-type: none"> i) Its operation are very simple ii) Performance and Speed control facility is easily available by using solid state devices such as SCR,IGBTs and microcontroller iii) It is comparatively clean and It is less noisy and pollution free iv) It is economical & more convenient 	<p>4 x1M</p>
<p>5 f)</p>	<p>Electroplating:</p> <p>Electroplating is defined as electrolytic process of depositing of one metal upon another metal.</p> <p>Purpose:</p>	<p>1M</p>



	<p>i) To protect the base metal from corrosion due to oxidation</p> <p>ii) To do plating of articles for decoration purpose</p> <p>iii) For repair work, For covering cheap metals by precious metals like gold, silver</p> <p>iv) One of the stage of manufacturing process</p> <p>Operations involved in electroplating:</p> <p>i) Cleaning of surface to be plated</p> <p>ii) Deposition of metal</p> <p>iii) Polishing the surface</p> <p>iv) Buffering</p>	2M									
		1M									
6 a)	<p>-Welding is the process of joining metals of similar composition by heating them to a suitable temperature with or without application of pressure and addition of filler material</p> <p>-In electric resistance welding type heavy current is passed through the work piece and heat is developed by the contact resistance of job is utilized in welding them together.</p> <p>-In electric arc welding , arc is a electric discharge between one electrode and another electrode which may be a work piece. The arc current while flowing through air in the form of electrons bombards the atoms in air and produces ions. Such state of matter is almost plasma state and the temperature in that vicinity is around 3000⁰ C to 4000⁰ C, which is generally two to three times the melting point of generally used metals such as copper, iron etc. The electric arc effectively concentrate heat on the surfaces it is desired to joins.</p>	1M 1.5 M 1.5 M									
6b)	<p>-To avoid electric accidents which may cause loss of human life, damage to equipments, machinery etc, Loss of production</p> <p>-To avoid fire due to electric reasons.</p> <p>-To avoid Electric shock.</p> <p>-To avoid Electric burns.</p>	1M 1M 1M 1M									
6c)	<table border="1"> <thead> <tr> <th>Sr no</th> <th>Incandescent Lamp</th> <th>Fluorescent Lamp</th> </tr> </thead> <tbody> <tr> <td>1</td> <td>Light output is affected by voltage fluctuations</td> <td>Voltage fluctuations has comparatively low effect on light output as the variations in voltage are absorbed in the choke</td> </tr> <tr> <td>2</td> <td>Initial cost per lamp is quite low</td> <td>Initial cost per lamp is more</td> </tr> </tbody> </table>	Sr no	Incandescent Lamp	Fluorescent Lamp	1	Light output is affected by voltage fluctuations	Voltage fluctuations has comparatively low effect on light output as the variations in voltage are absorbed in the choke	2	Initial cost per lamp is quite low	Initial cost per lamp is more	Any four points 4x1 M
Sr no	Incandescent Lamp	Fluorescent Lamp									
1	Light output is affected by voltage fluctuations	Voltage fluctuations has comparatively low effect on light output as the variations in voltage are absorbed in the choke									
2	Initial cost per lamp is quite low	Initial cost per lamp is more									



	3	Luminous efficiency per watt increases with increase in applied voltage	Luminous efficiency increases with the increase in wattage and length of tube	
	4	Its brightness is more	Its brightness is less	
	5	No Stroboscopic effect	It has objectionable stroboscopic effect	
	6	Its normal working life is about 1000 hrs	The life of the fluorescent tube is about 7500 hrs.	
	7	Heat radiations are present due to high working temperature	Heat radiations are negligible due to low operating temperature	
	8	For the same light output a large number of lamps are required which results higher wiring cost	For the same light output ,less number of tubes are required and therefore wiring cost is comparatively low.	
	9	It gives light close to natural light therefore , objects are seen properly	It does not gives light close to natural light ,therefore colour rendering is defective	
6 d)	In domestic wiring, Parallel connection is preferred. All domestic equipments/appliances are design for 230 V, hence appliances are connected in parallel across a main supply to get same voltage (i.e. 230 V) as of main supply voltage across each.			2M 2M
6 e)	i) <u>Totally Enclosed Non ventilated (TENV)</u> : This type is designed with totally enclosed to blocked the exchange of air between surrounded area and inside of the motor. But it is not fully enclosed because contaminated from outside could enter inside of motor through the seal of the shaft .The motor heat exchange through the enclosed by conduction process for small size .But for bigger size ,the frame designed with heavily ribbed to help dissipate heat more quickly. ii) <u>TEFC (Totally enclosed fan cooled)</u> :Prevents the free exchange of air between the inside and outside the frame but does not make the frame completely air tight. A fan is attached to the shaft and pushes air over the frame during its operation to help in the cooling process. The ribbed frame is designed to increase the surface area for cooling purpose . iii) <u>Explosion proof (EXPL)</u> :This is similar in design and appearance as TEFC type but for explosion proof enclosures are made from cast iron materials to stand from hazardous impact. iv) <u>Totally enclosed Wash down (TEWD)</u> : Designed to withstand high pressure wash downs or high humidity or wet or chemical environment.			1M 1M 1M 1M
6 f)	Importance of power factor improvement: i) For industrial and other big consumers has to pay electricity charges for his maximum			

