22643

23124 3 Hours / 70 Marks Seat No. Instruction : All Questions are *compulsory*. Marks 1. 10 **Attempt any FIVE :** (a) State the need of actuators in mechatronics systems. (b) Compare between pneumatic and hydraulic actuators. (c) State the need of air filters and regulators in pneumatic system. (d) Give the application areas of FMS. (e) State any two applications of hydraulic system. Give full form of AVG and state where it is used. (f) (g) State any four application areas of Robots. 2. 12 **Attempt any THREE :** (a) Explain the construction and working principle of LVDT. (b) Describe with sketches the building blocks of electrical system. Explain the working of single acting cylinder. (c) (d) Describe the operation of hydraulic pump. 3. 12 **Attempt any THREE :** (a) State the applications of following sensor : (i) Photo Electric Sensor (ii) Stroboscope (iii) LVDT (iv) Load Cell (b) State the applications, advantages and limitations of pneumatic system. (c) Describe the procedure to maintain hydraulic motors. (d) Draw block diagram of basic robotic systems and explain the function of each component.



4. Attempt any THREE :

- (a) Explain the construction and working principle of optical encoder.
- (b) Explain the system model of electromechanical system.
- (c) Describe the principle of operation of rotary actuators.
- (d) Describe the working of microcontroller based antilock brake system.
- (e) State the different types of direction control valve and explain operating principle of any one.

5. Attempt any TWO :

- (a) Draw and explain the block diagram of CIM (Computer Integrated Manufacturing). State its applications.
- (b) Draw block diagram of CNC based drilling machine and explain the function of each block.
- (c) Draw block schematic diagram of basic pneumatic system and explain each block.

6. Attempt any TWO :

- (a) Describe the working principle of pyro electric sensor. State its advantages and applications.
- (b) State the applications of the following mechanical motion elements :
 - (i) CAMS (ii) Gears (iii) Belts
- (c) Explain the working of microcontroller based pick and place robot with suitable sketch.

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