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23242 3 Hours /	70	Marks Seat No.
Instructions –	(1)	All Questions are Compulsory.
	(2)	Answer each next main Question on a new page.
	(3)	Illustrate your answers with neat sketches wherever necessary.
	(4)	Figures to the right indicate full marks.
	(5)	Assume suitable data, if necessary.
	(6)	Use of Non-programmable Electronic Pocket Calculator is permissible.
	(7)	Mobile Phone, Pager and any other Electronic Communication devices are not permissible in Examination Hall.
		Marks

1. Attempt any <u>FIVE</u> of the following:

- a) Draw ladder diagram of AND gate and NOT gate for PLC.
- b) List standard test inputs with their Laplace transform.
- c) Derive the transfer function of the given electrical circuit below (Fig. No. 1):



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- d) State need and benefits of PLC in automation. (any four)
- e) Find the poles and zeros of the following function

$$G(S) = \frac{(S+2)(S+3)}{(S+4)(S+1+j)(S+1-j)}$$

- f) Compare Open loop and Closed loop control system. (any four points.)
- g) Identify control system is faster or sluggish (slow) with respect to the
 - i) Wide proportional band
 - ii) Narrow proportional band

2. Attempt any THREE of the following:

a) Name the components labelled as 1, 2, 3, 4, 5. Redraw labelled diagram and identity the name of the block diagram. (Fig. No. 2)



- b) State mathematical equations of controller output for
 - i) ON-OFF Controller
 - ii) Proportional Controller
 - iii) PID Controller
- c) Describe different COMPARISON instructions with syntax used in ladder diagram.

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d) Identify the names of the components labelled as 1 and 2. State functions of component 1, 2 and 3 (Fig. No. 3)



3. Attempt any THREE of the following:

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a) The transfer function of the system is given by

$$T(S) = \frac{k(s+6)}{s(s+2)(s+5)(s^2+7s+12)}$$

Calculate

- i) Poles
- ii) Zeros
- iii) Characteristic equation
- iv) Order of the system
- b) Draw neat block diagram of Discrete DC input module for PLC.
- c) List input and output devices of PLC with their use. (Each four)
- d) Elaborate ON OFF controller with suitable example. State significance of neutral zone.

4.

- 12 Attempt any THREE of the following: Illustrate Fixed and Modular PLC in details. a) b) Classify various Control action modes of Controller. c) Identify following system based on roots located on S - plane. If all the roots of Characteristic equation lie on the left half i) of S - plane. If all the roots of Characteristic equation lie on the right half ii) of S - plane. If non repeated poles are located on the imaginary axis of iii) S - plane. If the poles are located far away from the imaginary axis of iv) S - plane.
 - d) Describe DC Servo System using suitable diagram.
 - e) Describe Relay instructions with symbols used in ladder programming for PLC.

5. Attempt any TWO of the following:

a) A unity feedback system has open loop function.

$$G(S) = \frac{10 (s+1)}{s (s+2) (s+5)}$$

Calculate

- Positional Error coefficient K_p i)
- ii) Velocity Error coefficient K_w
- Acceleration Error coefficient K_a iii)
- b) Describe the following terms of PLC in detail.
 - Scanning Cycle i)
 - Speed of Execution ii)
- c) Implement the following Boolean expressions using ladder programming.
 - i) Y1 = ABC + D(E+F)
 - $Y2 = \overline{A + B}$ ii)
 - iii) Y3 = AB

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6. Attempt any <u>TWO</u> of the following:

- a) Develop ladder diagram for following condition
 - i) When START push button pressed, then Motor M1 and RED light turns ON.
 - ii) GREEN light turns ON only when all A, B and C push buttons are pressed.
 - iii) YELLOW light turns ON when any one of the A, B or C push button pressed.
- b) Reduce the given control system using block diagram reduction techniques and obtain its transfer function. (Fig. No. 4)



c) Illustrate two special cases of Routh's Stability Criterion with suitable examples.