MAHARASHTRA STATE BOARD OF TECHNICAL EDUCATION

(Autonomous)
(ISO/IEC - 27001 - 2005 Certified)

Model Answer: Summer 2019

Subject: Advanced Surveying

(Pages: Total 15)

Sub Code: 17419

Important Instructions to examiners:

- 1) The answers should be examined by key words and not as word-to-word as given in the model answer scheme.
- 2) The model answer and the answer written by candidate may vary but the examiner may try to assess the understanding level of the candidate.
- 3) The language errors such as grammatical, spelling errors should not be given more importance. (Not applicable for subject English and Communication Skills.)
- 4) While assessing figures, examiner may give credit for principal components indicated in the figure. The figures drawn by the candidate and those in the model answer may vary. The examiner may give credit for any equivalent figure drawn.
- 5) Credits may be given step wise for numerical problems. In some cases, the assumed constant values may vary and there may be some difference in the candidate's answers and the model answer.
- 6) In case of some questions credit may be given by judgment on part of examiner of relevant answer based on candidate's understanding.
- 7) For programming language papers, credit may be given to any other program based on equivalent concept

Q. No.	Sub Q. No.		
Q.1. a)	1101	Attempt ANY SIX of the following	12M
	i)	Define 1) Contour interval: 2) Horizontal equivalent	2M
	Ans	Contour interval: - The vertical distance between two successive contours is called "Contour Interval". Horizontal equivalent: - The horizontal distance between any two successive contours is called "Horizontal Equivalent".	1M each
	ii)	State any two uses of contour map.	2M
	Ans	 The nature of the ground surface or topography of a country whether hilly, undulating orflat can be understood. Possible routes of communication between two different places can be known. The capacity of a reservoir or the area of catchment can be determined approximately. The visibility of points can be established. A suitable route for a given gradient can be marked on the map. The suitable site for most economical alignment can be selected for any engineeringprojects like dams, canals, roads, sewers, railways, etc. A section of the ground surface can be drawn in any direction from the contour map. 	1M each (any two)

		8) Quantities of earthwork can be determined approximately.						
	iii)	Define zero circle .	2M					
	Ans	For a mechanical or polar planimeter, when the tracing point moves along a						
		circle without rotation of the wheel i.e. when the wheel just slides without	2M					
		any change in reading, the circle is known as the zero circles.						
	iv)	Define swinging and transiting.	2M					
	Ans	Swinging: It is the process of turning the telescope in horizontal plane.						
		Transiting: It is the process of turning the telescope through 180° in a vertical plane about its horizontal axis.						
	v)	Define axis of telescope and horizontal axis.	2M					
	Ans	Axis of telescope:-It is the line joining the centre of eye piece to the optical						
		centre of object glass.	1M each					
		Horizontal axis: - The axis about which telescope can be rotated in vertical						
		plane.						
	vi)	State any two situations where tachometry is used.	2M					
	Ans	1) When obstacles such as steep and broken ground, stretches of water or						
		swamps.	1M each					
		2) In rough country both horizontal and vertical measurements are tedious.	(for any two)					
		3) In locating contours and filling in detail in a topographic survey.	two					
	vii)	State any two features of digital level.	2M					
	Ans	1) It has minimum display resolution of 0.1 mm.						
		2) It can obtain elevation and distance digitally. Height range is from 0 to						
		4.05 m and distance range is from 1.6m to 100m.						
		3) It can be used as a conventional automatical level with traditional dumpy	1M each					
		level.	(any two)					
		4) It is waterproof instrument and can be used in harsh atmospheric	(110)					
		conditions.						
		5) It has a rechargeable battery.						
	viii)	State any two methods of setting out curve.	2M					
	Ans	1) Chain and tape method (Linear method)						
		a) By offsets from long chord.						
		b) Versine method of successive bisection of arcs						
		c) Offsets from tangents	1M each					
		d) Offsets from chord produced	(for any					
		2) Instrumental Methods	two)					
		a) By Rankine's method of tangential angle (or deflection angle)						
		b) Two theodolite method						
	14	c) Tacheometric method						
Q1b)	۵	Attempt any <u>TWO</u> of the following.	8M					
	i)	Draw a neat sketches of contour for following						
		1) Ridge line						
		2) Valley line	4M					
		3) Steep slope						
		4) Depression						

Ans	97	
	97 98 99 Po Pidge line 100 99 96 Valley line	1M each
	Depression Steep slope	
***	Define Demokratic State the manifest for the second manifest and manifest the second m	
ii)	Define Remote sensing. State the meaning of active and passive system.	4M
Ans	Remote sensing: The method of collecting and interpreting information	
	about terrain and other objects from a distance withoutbeing in physical contact with the object.	2 M
	Active System: - The system in which irradiance from artificially generated	
	energy sources such as radar is used then it is called as active system.	1 M
	Passive System: - the system in which sun and earth's material are used as	0.22
	natural source so as to radiate electromagnetic energy of variable wave	1 M
****	length is called as passive system	
iii)	State the procedure for measurement of vertical angle by transit the dolite with suitable sketch.	4M
Ans		
7 1113	Object	
		1M (for
		sketch)
	A vertical angle is the angle between the inclined line of sight and the	
	horizontal.	
	Procedure :-	3M*
	1) Set up the thedolite and level it carefully with reference to the altitude	(for procedu
	bubble. Place the altitude bubble parallel to any two screws and bring the	re)
	bubble to the centre by turning both the foot screw inside or outside. Rotate	
	the telescope through 90^{0} so that the altitude bubble is on the third foot	

	1					
		screw. Bring this procedure till the bubble is central in both the positions.				
	2) Loosen the vertical circle clamp and direct the telescope in vertical plane					
		towards the object, and bisect it exactly using the vertical circle tangent				
		screw.				
		3) Read both the verniers C and D. The mean of the two gives the vertical				
		angle.				
		4) Change the face of the thedolite and repeat the process. The mean of the				
		two readings gives the second value of vertical angle. The average of the				
		two values i.e. face left and face right, gives the values of the required				
		angle.				
		*(Note: Above procedure is applicable for theodolite having fixed				
		vertical verniers. If procedure for non fixed vertical verniers is written,				
		it may be accepted.)				
0.2	1	() Destruction for the Control of Auditor ()	101			
Q.2		Attempt FOUR of the following	16M			
	a)	State the methods of contour interpolation and explain any one.	4M			
	Ans	Methods of interpolation.				
		i) By Arithmetic calculations	1M			
		ii) By Estimation	(for			
		iii) By Graphical method	methods			
		i) By Arithmetic Calculation: This is very tedious but accurate method and)			
		is used for small areas where accurate results are necessary. The contours				
		are interpolated as under: Suppose A and B are two points at a distance of				
		30 m and the reduced level of A and Bare 25.45m and 27.54m respectively				
		.Taking the contour interval as1m, 26 and 27 m contours may be				
		interpolated in between A and B. The difference of level between A and B	3M			
		is 2.09m. The difference of level between A and 26m, and A and 27m is	(for any			
		0.55m and 1.55 mrespectively. Therefore the horizontal distance between A	one method)			
		and 26 m contour =0.55/2.09 x 30m and between A and 27 m	method)			
		contour=1.55/2.09 x 30m. These distances are then plotted to scale on the				
		map.				
		ii. By Estimation Method				
		1. Contour points are estimated by judgment and marked .The contour lines				
		are then drawn through these points.				
		2. This method is rough and is suitable for small scale works				
		3. This points located by judgment are not accurate as located by arithmetic				
		calculations.				
		iii. By Graphical Method				
		The same of the sa				
		Several lines are drawn parallel to each other on a tracing paper say at an				
		interval of 0.5 m. In fig the bottom most line represent an elevation of				
		80.00m and if it is required to interpolate contour of 81.5,82 and 82.5				
		between a line PQ of an elevation of 80.00m and 84.00 m, then keep the				
		tracing paper on the line in such a way that point P may lie on a parallel				
		representing an elevation of 80.00 m. Now, rotate the tracing paper on				
		drawing in such a way that point Q may lieon parallel representing an				
		elevation of 84.00m. The points atwhich the parallel representing 81.5, 82.0				
		and 82.5m (shown by X, Y,Z in fig.)may now be pricked through the				

	position of the contour points on line PQ. 85 84.5 84 83.5 82.5 82 81.5 81 80.5 80	
b)	State any four fundamental characteristics of contour line.	4M
Ans	 All points on a contour line have same elevation or RL. Two contour lines of different elevation can not intersect each other except in case of overhanging cliff. When contour lines comes close together then it indicate steep slope. If contour lines are equally spaced, uniform slope is indicated. Closed contour lines with higher values inside indicates hill. Closed contour lines with lower values inside indicates depression. 	1M (each for any four)
c)	Describe the procedure to locate grade contour in a field.	4M
Ans	In preliminary survey for a road in hilly or mountaneous country, the points are fixed along the given gradient. The line joining such points is called a contour gradient or grade contour. It may be located first approximately by Abeny level and then level may be used for accurate location. Illustration: Suppose a falling gradient of 1 in 30 is to be traced on ground	1M (for definitio n)
	Let the RL of starting point =275.300 m Let the distance of next point =40 m. Let back sight of 0.400 m is taken on starting point. H.I.=275.300 + 0.400 = 275.700 m. RL of the next point =275.300 - 40/30 = 273.97 m. Hence the required saff reading =275.700 - 273.970 = 1.73 m. The staff is then held at 40 m from starting point and is moved radially up or down the slope until the reading of 1.73 m is obtained. The point is marked by fixing a peg. The process is repeated until the last point is marked.	3M (for descripti on)
d)	State different relationship between fundamental axis of theodolite.	4M
Ans	The desired relationships between fundamental axes of transit theodolite when in perfectadjustment are: 1) The axis of plate level must be perpendicular to the vertical axis. 2) The line of collimation must coincide with optical axis of telescope and should be perpendicular to the horizontal axis. 3) The horizontal axis must be perpendicular to the vertical axis. 4) The axis of telescope (axis of bubble tube) must be parallel to the line of collimation.	1M (Each for any four)

		5) If the instrument has fixed vernier for vertical circle, it must read zero in						
		leveledposition.						
	e)	Describe the procedure for measuring magnetic bearing by transit	4M					
		theodolite with suitable sketch.						
	Ans	Q P	1M (for fig.)					
		 Attach trough compass or circular box compass to theodolite at the place provided. Set up the instrument over the station P, and level it. Set the vernier A to 0 ° of the horizontal circle. Unclamp the lower plate and release the magnetic needle and rotate the instrument about it's outer axis until the magnetic needle shows North and South direction exactly. Loosen the upper plate turn the telescope and bisect the station R exactly by using upper clamp and it's tangent screw. Read both the verniers. The mean of the two reading gives the magnetic bearing of line PR. 	3M (for procedu re)					
	f)	State any four uses of theodolite.	4M					
Q.3	a) Ans	ii)To measure horizontal and vertical angles. iii)It can be combined with EDM to measure horizontal andvertical distances. iii) To measure horizontal and vertical distances using principle of tacheometry. iv) To mark line out of complicated and large buildings. v)To mark alignment of road, railway, canal. vi) It can be used for prolonging straight line. Attempt any FOUR of the following List any four modern surveying instruments. Following are the modern surveying instruments i) Total Station ii)One Second Micro-optic Theodolite iii) Electromagnetic Distance Measuring Instrument (E.D.M.) iv) Electronic Digital Theodolite v) Digital level vi) Aerial Camera	1M each (for any four) 16M 4M 1M each (any four)					
	b)	Discuss any four advantages of total station area discuss level	AM					
	b) Ans	Discuss any four advantages of total station over dumpy level. Advantages of total station over dumpy level:-	4M					
	AllS	1) Total station gives digital measurements of sloping, horizontal and vertical distances accurately and precisely. 2) Total station gives digital measurements of vertical and horizontal angles accurately and precisely. 3) Total station consists of electronic field book to record the data and	1M each (any four)					

1	Residence Control Cont			
	additional information.			
	4) Total station is used for speedy completion of any type of project work.			
	5) Total station provides the provision of uploading and downloading the			
	data to computer.			
- >	6) Total station used to prepare the map and drawings using softwares.	43.4		
c)	State any four component parts of digital level and state their purpose.	4M		
Ans	Following are the component parts of Digital Level:	134		
	1. Display screen: To show the program is going on. It has high resolution.	1M each		
	2.Key Pad- For operating the instrument	(any		
	3.Telescope- For bisecting the object at longer distance with high precision	four)		
	4. Foot screws - For leveling purpose			
	5. Focusing screw- Internal focusing is provided, so as to observe the object			
 4)	clearly, it is focused with focusing screw.	4M		
d)	State any four application of digital theodolite.	4101		
Ans	Application of digital theodolite:-	1M soah		
	To measure horizontal angle very precisely up to one second. To measure vertical angle accurately up to one second.	1M each		
	2. To measure vertical angle accurately up to one second.	(any		
	3. Primary, secondary, and tertiarytriangulation work can be completed precisely and speedily.	four)		
	4. For long road and railway bridges, for aligning piers and for determining			
	their centre to centre distance digital theodolite can be used.			
	5. To determine horizontal distance more precisely.			
e)	Describe the procedure to setup total station.	4M		
Ans	Following steps are followed for the set up of total station	4111		
Alls	1. Set up the tripod approximately over the station point.			
	2. Remove the plastic cap from tripod and make tripod nearly level by			
	stretching tripod legs.			
	3. Now fix the total station on tripod and roughly leveled and centered the			
	instrument andpush each leg firmly into the ground.			
	4. Check the level and center it again . Adjust level by changing leg length.			
	5. Adjust the three screws of the tribrach to center the bubble of spirit level			
	by using threefoot screws.			
	6.Accurate leveling is done by using foot screws.			
	7. Focusing of eyepiece and object glass is done.			
	8.Check the plate level from time to time during measurement.			
	9. If total station is used at subsequent stations, proper orientation is to done.			
f)	Draw a neat sketch of circular curve show all the elements.	4M		
Ans				
	Angle of intersection B θ = Deflection angle			
	Simple circular curve			
	E Simple director			
	T ₂ / Second or forward tangent at T ₂	2M		
	Back tangent T1 D T2 tangent at 12	(for		
	or first tangent at T1	sketch)		
	0/2 - 0/2 A			
	C/ R B			
	Where:			
	AB and BC are two tangents.			
	1970	1/2 M		

	1	BT ₁ and BT ₂ are lengths of tangents.	each
		BE is Apex distance.	(Any
		DE is Versed sine.	four)
		R is Radius of curve.	1041)
		T_1DT_2 are length of long chord.	
		T ₁ ET ₂ is the length of curve.	
		I is an angle of intersection.	
		○ is deflection angle	
		T ₁ and T ₂ are tangent points.	
0.4	-	Point B is point of intersection. Attempt any FOUR of the following	16M
Q.4	-		101/1
	a)	The following readings were obtained when a figure was traversed	
		using a planimeter in clockwise direction with anchor point outside	
		and with tracing arm set to the natural scale (M= 100 sq.cm) The zero	4M
		marks of the disc passed the index mark once in the clockwise(positive)	
		direction. IR = 9.625, FR = 1.224. Calculate the area of the figure.	
	Ans	Initial reading, I.R. = 9.625,	
		Final reading, F.R. = 1.224	
		$M = 100 \text{ cm}^2 \text{ and } C = 0 \text{ (Anchor point outside the figure)}$	
		N=1	
		Area = M (F.R. – I.R. \pm 10 N +C)	2M
		Area = $100 (1.224 - 9.625 + (10 X 1) + 0)$	1M
		Area= 159.9 cm ²	1M
	b)	State the practical applications of remote sensing in civil engineering field.	4M
	Ans	1) Silting of storage reservoirs harbors etc. – Remote sensing technique	
	1.222	that makes use of satellite imagery (in the infrared region) gives idea about	1M each
		the silting of reservoir qualitatively and to some extent quantitatively.	(any
		2) Location of Percolation Tanks – The exact location of percolation	four)
		tanks can be carried out with the help of remote sensing technique, keeping	1011)
		in view that the site required for location of percolation tanks should be on	
		permeablefoundations.	
		3) Revision of existing toposheets - The rapid revision and updating of	
		existing topo (graphical) sheets can be carried out speedily with the help of	
		aerial photography (which is also a branch of remote sensing) and satellite	
		imagery.	
		4) Alignment of new highways and rail routes – The location of most	
		economical alternative sites for such works can very well be carried out	
		speedily by making use of aerial photographs and satellite imagery.	
		5) Location of Bridge site: The existing foundation condition along the	
		proposed bridge construction site can be ascertained with the help of aerial	
		photographs and or satellite imagery.	
		6) Location of Dam sites: For gravity, geological investigations of the	
		existing rock in and around the proposed dam site can be carried out by	
		aerial photographs and or satellite imagery. Geological features such folds,	
		faults, dykes, fractures etc. can be determined by the remote sensing	
		technique.	
		7) Tunneling: Remote sensing i.e. aerial photography and or satellite	
		imagery of the area helps in furnishing all such information and thus ensures	
	1	the entaty of tunnal during its construction stages	
		the safety of tunnel during its construction stages.	
		8) Seepage losses in canals: Monitoring of soil moisture in and around the canal system can be possible by remote sensing technique i.e. by careful	

	study of aerial photographs and satellite imagery of such areas.	
(c)	State any four applications of GIS.	4M
Ans	Applications of GIS:- 1) Map making 2) Site selection 3) Mineral Exploration 4) Land use planning and management 5) Environmental Impact studies 6) Natural Hazard mapping or assessment 7) Water Resources availability.	1M each (any four)
d)	Explain principle of tachometry with suitable sketch	4M
Ans	Principle of tachometry is based on principle of similar triangle in which	41/1
	correspondingsides & altitudes are proportional. The ratio of distance of base from apex and length of base is always Constant. In fig. $O_1a_1a_2$, $O_1b_1b_2$, $O_1c_1c_2$ are all isosceles triangles where D_1 , D_2 , D_3 are the distances of bases from the apices and S_1 , S_2 , S_3 are the Lengths of the bases. According to stated principle. $D_1/S_1 = D_2/S_2 = D_3/S_3 = f/i$ =Constant Where f=focal length of objective and i= stadia intercept	2M 1M
		43.4
e) Ans	State any four characteristic of tachometer. 1. The value of constant (f/i) = 100.	4M
Alis	 The value of constant (1/1) = 100. The telescope should be powerful, the magnification should be 20 to 30 times the diameter The telescope should be fitted with anallatic lens to have the value of (f +c) = 0 The vision through the telescope should give a clear and bright image at a long distance. The aperture of the objective should be 35 to 45mm in diameter in order to have a sufficiently bright image. 	1M each (any four)
f)	Give the classification of curve and Define	4M
	1.Transition curve 2. Reverse curve	X 5-Y 0.00
Ans	Classification of curve is as follows- 1) Horizontal curve a) Simple curve b) Compound curve c) Reverse curve d) Transition curve e) Lemniscate curve	1M

	T	2) Vertica	Louevo								
		a) Summit							1M		
		b) Valley of							IIVI		
				A curve of	variable	radine	ie known	as a transition			
			Transition curve:- A curve of variable radius is known as a transition curve. In railways ,such a curve is provided on both sides of a circular curve								
		I .	e super ele		s provide	d on be	our sides or a	a circular curve	1M		
		The second secon			consist	of two	arce bandi	ng in opposite	1M		
								~	IIVI		
		1		ers he on o	pposites s	sides of	the curve.	They have one			
Q.5	-	Attempt o		f the fellow	dna				16		
Ų.S	a)			f the follow		noction	with a clos	ad travarca	10		
	a)	PQRSP.	villg data v	as conecte	u m com	iection	with a clos	eu traverse			
		Line Length Bearing									
		PQ 780 133°45′									
								8M			
				QR					OIVI		
				RS	390	340°(00				
				SP	?	?					
				g length of		oearing	g of SP.				
	Ans			luced Bearing of $PQ = 180^{\circ}$		5′- S46°	15 E				
				of QR = 32° 2			13 L				
				of $RS = 360$							
		Step 2) Calci	ulation of Lat	titude:					OME		
		Lattitude of	Line PQ= lcos	s⊖= 780cos46	5°15'= - 53	9.38(as lin	ne going towards so	outh is considered as -ve)	8M*		
		Lattitude of	Line QR= Ico	s⊖=2000cos3	$2^{\circ}24 = 168$	88.65 (as l	line going towards	north is considered as			
		50.00	Line RS= lcos	s⊖=390cos20	° = 366.48	(as line goir	ng towards north is	considered as +ve)			
		Step 3) Calci	ulation of Dep	parture:							
		Dej considered as +ve		$e PQ = lsin\Theta$	= 780sin46	5°15′= 56	53.44(as line going	g towards east is			
		Dej considered as +ve		$e QR = Isin\Theta$	= 2000sin3	$32^{\circ}24 = 1$	1071.65(as line g	oing towards east is			
		Departure of	Line $RS = Is$	$in\Theta = 390sin2$	20° = -133.	38 (as line	going towards wes	t is considered as -ve)			
			ulation of Lat	titude and Dep	parture of I	ine SP					
		77.77	688.65+366.4								
				1515.75+L=	=0						
			f line $SP = -1$:								
			of all departu								
		∴ 563.44 + 1071.65-133.38+D=0 1501.71+D=0 ∴Departure of line SP = -1501.71 Step 5) Calculation of length and bearing of line SP Length of SP = $\sqrt{L^2 + D^2} = \sqrt{1515.75^2 + 1501.71^2} = 2133.68\text{m}$ $\tan\Theta = \frac{D}{L} = \frac{1501.71}{1515.75} = 0.990$									
		$\Theta = \tan^{-1}(0.990) = 44^{\circ}44^{\circ}$ ∴Reduced Bearing of SP = S44°44′W									
				$SP = 180^{\circ} + 4$	4°44′ = 22 4	4°44′					
		Step 6) Tabl									
		Line	Length	Bearing	Redu	2000	Lattitude	Departure			
			12.5		Bear		10 22 60 2 61 1 35 6 60 00				
		PQ	780	133°45′	S46°		- 539.38	563.44			
		QR	2000	32°24′	N32°	200000000000000000000000000000000000000	1688.65	1071.65			
		RS	390	340°00′	N20		366.48	-133.38			
		SP	2133.68	224°44′	S44°4	4 W	-1515.75	-1501.71			

	departure o of line SP 1	f lines 1 M,ca M, length of lin	lculation latitude e SP 1 M, RB of	itudesof lines 1 l line SP 1 M, Cald line SP 1 M, WCE					
b)	calculate th	•	nt co-ordinate	es from follow	ing data show	ing			
		Lat	titude	Depar	ture				
	Line N S E W								
	AB		182.63	313.12		8M			
	BC	244.72		470.12	210.24	32.2			
	DE	495.17	268.70		318.34 388.46				
	EA		288.27	2	113.34				
Ans		tion of Northir	ng and Southings		110.04				
	Error = Summa Eastings = 313 Westings = 31 Algebra Error = Step 2) Calcul Correc Arithm Correc Correct Correct Correct Correct Correct Correct Correct	0.29(error +ve correction of Easting 5.12+470.12=73 8.34+388.46+1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	and Westing 83.24 113.34=820.14 artures = 783.24 prection should be-year cted latitudes by $= \frac{\text{latitude of t}}{\text{airthmatical sum of t}}$ $= \frac{182.63}{1479.49} \times 0.2$ $= -182.63-0.035 = \frac{4.72}{79.49} \times 0.29 = 0.047$ $= 244.72-0.047 = 2$	- 820.14 = -36.9 transit rule. hat side of all latitudes 9.6=1479.49 9 = 0.035 -182.665	error in latitude	2M			

Correction to latitude EA =
$$\frac{288.27}{1479.49}$$
 x0.29 = 0.059

Corrected latitude EA = -288.270-0.059 = -288.329

Step 3) Calculation of Corrected Departures by transit rule.

Correction to departure = $\frac{\text{departure of that side}}{\textit{airthmatical sum of all departure}} x total \ error \ in \ departure$

2M

Arithmetic sum of departuress = 783.24+820.14=1603.38

Correction to departure AB =
$$\frac{313.12}{1603.38}x36.9 = 7.206$$

Corrected departure AB = 313.12 + 7.206 = 320.326

Correction to departure BC =
$$\frac{470.12}{1603.38}$$
 x36.9 = 10.819

Corrected departure BC = 470.12 + 10.819 = 480.939

Correction to departure CD =
$$\frac{318.34}{1603.38}$$
 x36.9 = 7.326

Corrected departure CD = -318.34 +7.326=-311.014

Correction to departure DE =
$$\frac{388.46}{1603.38}$$
 x36.9 = 8.940

Corrected departure DE = -388.46 + 8.940 = -379.520

Correction to departure EA =
$$\frac{113.34}{1603.38}$$
 x36.9 = 2.609

Corrected departure EA = -113.34 + 2.609 = -110.731

Step 4) Table of corrected consecutive coordinates and Independent coordinates.

Line	Corre	cted Cons	secutive coo	Independent Cordinates			
	latti	tude	depa	rture			
	N	S	Е	W	N	Е	
AB		182.665	320.326		B=817.335	1320.326	
BC	244.673		480.939		C=1062.008	1801.265	
CD	495.073			311.014	D=1557.081	1490.251	
DE		268.752		379.520	E=1288.329	1110.731	
EA		288.329		110.731	A=1000.000	1000.000	
Sum	739.746	739.746	801.265	801.265			

Sample calculation for Independent co-ordinates

Assume north co-ordinate of A=1000

Deduct southing of AB = -182.665

North Co-ordinate of B =817.335

Add northing of BC =+244.673

North Co-ordinate of C = 1062.008

Continued until A is reached

2M

		Assume East co-ord	linate of A=100	0					
		Add easting of AB	=+320	226					
		East Co-ordinate of B =1320.326							
		Add easting of BC = 480.939							
		East Co-ordinate of	C = 1801.2	65					
			SEC. (1998) 199 HV. 1995 HV.						
		Continued until A is							
	c)	A Tacheometer	fitted with ar	nallatic lens w	as set up at sta	ation O and	d the		
	65/2	following readings were taken on staff held vertical.							
		Inst.St.n	Staff St.n	Vertical An			8N	Л	
		0	BM	+7°30′	0.900,1.2		OIV.	1	
		O Find the benine	B mtol distance	-2°30′	1.100,1.3		M in		
		Find the horizon 50.000m. Take			KT OI .B. II	KL OF B	VI IS		
		Solooni. Take	me constant a	as 100.					
	Ans	Step 1: To find the	height of Instr	ument (HI)					
		Instrument statio							
		Angle of elev	ation = $\Theta = 7^{\circ}$ 3	30′					
		Staff Intercept	netant 1M						
		Multiplying Constant $=\frac{f}{i}$ = 100 and anallatic lens fitted : additive constant							
		=(f+c)=0.							
		Vertical distance	$ce = V_1 = \frac{f}{f} S \frac{sin}{f}$	$\frac{n2\theta}{c} + (f+c)\sin\theta$	$\theta = 100 \times 0.6^{\frac{\sin^2 x}{2}}$	$\frac{2(7^{\circ}30')}{2} + 0$	13/	1	
			= 7.76n			2	1M	4	
		∴ H.I.= BM+h ₁ - V	$V_1 = 50 + 1.2 - 7.76$	6 = 43.44m			1N	Л	
		Stop 2 : To find the	horizontal dis	tongo OP and E	OL of D				
		Step 2 : To find the Instrument statio							
		Angle of depr							
		Staff Intercep							
		Horizontal Distan	2N	1					
		= 49.904m (Ans)	2/73/2002						
		Vertical distance =	1N	1					
		.DI -eD III	2N	Л					
		∴R.L.of B = H.I	$-V_2-n_2 = 43.44$	4 – 2.17- 1.350	= 39.92 m (Ans)		210	1	
Q.6	Attempt any TWO of the following:								
2.0	a)	16N							
		The area enclose Contour(r		255 26		270			
		Area(m ²)	2080	8500 16	500 25200	33700			
		Calculate tne vo	lume of wate	r between 250	Om and 270m b	у	8N	1	
	A	Stan 1 - To coloule	to the Volume	V by neina tran	azoidal formula				
	Ans Step 1 : To calculate the Volume V by using trapezoidal formula								
	Alis	Step 1 . To careara							
	Alis	# - E			5200 , A ₅ =33700				

	Py Transzaidal Formula :	
	By Trapezoidal Formula; Volume $V = \frac{D}{2} \{A1 + A5 + 2(A2 + A3 + A4)\}$ where D= common distance between sections	2M
	$= \frac{5}{2} \{2080 + 33700 + 2(8500 + 16500 + 25200)\}$	
	$= 2.5 \{136180\}$ $= 340450 \text{ m}^3$	2M
	= 340450 m Step 2 : To calculate the Volume V by using Prismoidal formula	
	Step 2. To calculate the volume v by using trismoldar formula	
	Let A_1 =2080 , A_2 =8500 , A_3 = 16500 , A_4 =25200 , A_5 =33700 By Prismoidal Formula ;	
	2, 1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.1.	21/1
	Volume V= $\frac{D}{3}$ {A1 + A5 + 4(A2 + A4) + 2(A3)}where D= common distance between sections	2M
	$= \frac{5}{3} \{2080 + 33700 + 4(8500 + 25200) + 2(16500)\}$	2M
	$= 339300 \text{ m}^3$	2111
ŀ	State any four features and any four applications of total station.	8M
A	ns Following are features of total station.	
	High accuracy and long measuring range.	
	a) Higher accuracy: ±(2mm + 2 ppm)	
	 b) Long measuring range with mini prism is 0.9km. 	
	c) Long measuring range with single prism is 2.0km.	
	d) Long measuring range with 3 prism is 2.7km.	4M
	2. Versatile application program.	4M
	a) On board data collection, stakeout/ survey road calculation and	(any four)
	many more functions.	ioui)
	b) Integrated alphanumeric key realizes the quicker operation.c) Large internal memory up to 24000 points.	
	3. Enhanced absolute encoder	
	a) Adopted absolute encoder which need not require zero set and it	
	can also realize stable measurement with less reading error.	
	b) Superior water-resistant and dust proof.	
	c) No worry about sudden bad weather.	
	Following are applications of total station.	
	With the help of electronic total station, measurement of slope	
	distance, horizontal and vertical distance can accurately and	
	precisely found out.	
	2. Electronic total station gives the complete basic surveying exercise	4M
	in order to appreciate how land survey measurements can be used in	(any
	support of engineering construction and environmental restoration	four)
	activities.	
	3. Vertical angle and horizontal angle are accurately measured by	
	electronic total station.	
	4. Total station for levelling classified as the indirect levelling method	
	and since it is judged that the method can maintain the considerable	
	accuracy, now it has been increasingly used for many public works	
	as road, airport and city etc.	
	5. Layout of complicated and large projects can be given.6. Area of field of any shape can be calculated	
	o. Area of field of any shape can be calculated	

(c)	Calculate the ordinates on long chord at 5 m interval for a circular curve at radius zoom and long chord of 60 m.	8M		
Ans	Given:			
	a) Interval on long chord = 5m			
	b) Considering Radius of curve =R= 200m			
	c) Length of long chord = L=60m			
	By offsets from long chord method,			
	We know,			
	Mid-ordinate = $O_0 = R - \sqrt{R^2 - (L/2)^2}$	2M		
	$=200 - \sqrt{200^2 - (60/2)^2}$			
	= 2.26m	1M		
	The ordinates calculated at 5 m intervals starting from the center towards	23.4		
	the tangent point of left half.	2M		
	$O_5 = \sqrt{R^2 - x^2} - (R - O_0)$			
	$=\sqrt{200^2-5^2}$ - (200-2.26)			
	= 199.93- 197.73	1/2M		
	= 2.19 m			
	$O_{10} = \sqrt{R^2 - x^2} - (R - O_0)$			
	$=\sqrt{200^2-10^2}-(200-2.26)$			
	= 199.74-197.73			
	= 2.01	1/2M		
	$O_{15} = \sqrt{R^2 - x^2} - (R - O_0)$			
	$=\sqrt{200^2-15^2}-(200-2.26)$			
	= 199.43-197.73	1/23.5		
	= 1.69 m	1/2M		
	$O_{20} = \sqrt{R^2 - x^2} - (R - O_0)$			
	$= \sqrt{200^2 - 20^2} - (200 - 2.26)$			
	= 198.99-197.73	1/2M		
	= 1.25 m	1/21/1		
	$O_{25} = \sqrt{R^2 - x^2} - (R - O_0)$			
	$= \sqrt{200^2 - 25^2} - (200 - 2.26)$			
	= 198.43-197.73	1/2M		
	= 0.69 m			
	$O_{30} = \sqrt{R^2 - x^2} - (R - O_0)$			
	$= \sqrt{200^2 - 30^2} - (200 - 2.26)$			
	$= \sqrt{200^2 - 30^2 - (200^2 - 2.20)}$ $= 197.73 - 197.73 = 0 \text{m}$	1/2M		
	(Note: Value of radius of curve assumed by student other than 200 m may			
	be considered and the respective values of ordinates should be checked by			
	performing calculations.)			