

Subject Name: BEM

<u>Model Answer</u>

Important Instructions to examiners:

- 1) The answers should be examined by key words and not as word-to-word as given in the model answer scheme.
- 2) The model answer and the answer written by candidate may vary but the examiner may try to assess the understanding level of the candidate.
- 3) The language errors such as grammatical, spelling errors should not be given more Importance (Not applicable for subject English and Communication Skills.
- 4) While assessing figures, examiner may give credit for principal components indicated in the figure. The figures drawn by candidate and model answer may vary. The examiner may give credit for any equivalent figure drawn.
- 5) Credits may be given step wise for numerical problems. In some cases, the assumed constant values may vary and there may be some difference in the candidate's answers and model answer.
- 6) In case of some questions credit may be given by judgement on part of examiner of relevant answer based on candidate's understanding.
- 7) For programming language papers, credit may be given to any other program based on equivalent concept.

Q.	Sub	Answer	Marking
No.	Q. N.		Scheme
1	a (i)	Draw symbol and label the terminal of:	
		1. Photo diode 2. UJT	
			1 M each
		Anode Cathode E	
		Photodiode symbol	
	ii)	Define Intrinsic and Extrinsic semiconductor.	1 M each
		Intrinsic- The pure form of the semiconductor is known as the intrinsic semiconductor	I W each
	iii)	Extrinsic- The semiconductor in which intentionally impurities are added for making it conductive is known as the extrinsic semiconductor.	
	,	List types of BJT and draw symbols of the same with neat labels	
		Types - NPN transistor & PNP transistor	List - 1 M
			Symbol-







	digitally controlled combustion engines, robots, automated guided vehicles home appliances such as dish washer and wash automatic air conditioning systems unmanned aerial vehicles and automatic pilot	-	1 M eac
viii)	State types of real time mechatroni	ics system	1 M eac
В	 Hard real-time: missing deadlines may cause of Examples: Airbags, ABS Soft real-time: meeting deadlines is desirable in not critical Examples: command interpreter of the user in Compare microprocessor and microcom 	for performance reasons, but missing them is terface	
i)	Microprocessor	Microcontroller	
	Do not have inbuilt RAM or ROM	Inbuilt RAM or ROM	1 M to
	Do not have inbuilt Timer	Inbuilt Timer	each
	I/O Ports are not available, it required	I/O Ports are available	point
	8255 for interfacing		
	Do not have inbuilt serial port, it required	Inbuilt serial port	
	extra devices like 8251.		
	Program and data are stored in same	Separate memory to store program and	
	memory.	data	
	Boolean operation is not possible directly	Boolean operation is possible	
	Many instruction to access external	Few instructions for external memory	
	memory access.	access	
	Less multifunction pins on the IC	Many multifunction pins on the IC	
B ii)	Sketch circuit diagram of non-inv Rf=25KΩ, Ri= 5KΩ Non-Inverting Amplifier	verting Op-amp. Calculate gain if	
	R^{1} R^{2} $A_{V} = 1 + \frac{R^{1}}{R^{2}}$		Dia- 2 N



2.

MAHARASHTRA STATE BOARD OF TECHNICAL EDUCATION (Autonomous) (ISO/IEC - 27001 - 2013 Certified) SUMMER- 18 EXAMINATION

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В List any four advantages and applications of CNC system iii) Advantages:-1. CNC machines be used continuously 24 hours can а dav. 2 M each 2. CNC machines are programmed with a design which can then be manufactured hundreds or even thousands of times. Each manufactured product will be exactly the same. **3.** Less skilled/trained people can operate CNCs unlike manual lathes / milling machines etc.. which need skilled engineers. **4.** CNC machines can be updated by improving the software used to drive the machines 5. CNC machines can be programmed by advanced design software such as Pro/DESKTOP^{*}, enabling the manufacture of products that cannot be made by manual machines, even those used bv skilled designers engineers. **6.** Modern design software allows the designer to simulate the manufacture of his/her idea. There is no need to make a prototype or a model. This saves time and money. 7. One person can supervise many CNC machines as once they are programmed they can usually be left to work by themselves. **Applications-**- Lathe machine - milling machine - grinding unit - sheet metal press machine - tube bending machine а - welding machine What is thermal runaway? How it is avoided? 2 M each **Thermal runaway** The problem with increasing temperature causing increasing collector current is that more current increase the power dissipated by the transistor which, in turn, increases its temperature. This self-reinforcing cycle is known as *thermal run away*, which may destroy the transistor. To avoid thermal runaway a heat sink is used. A heat sink is a passive heat exchanger that transfers the heat generated by an electronic or a mechanical device to a fluid medium, often air or a liquid coolant, where it is dissipated away from the device, thereby allowing regulation of the device's temperature at optimal levels. b. Draw instrumentation amplifier and write its output voltage equation Draw-3



	Sul	bject Name: BEM <u>Model Answer</u> Subject Code: 17302	
		SIG - Rf Rg R1 SIG + V_O = [(Sig +) - (Sig -)]x $\begin{bmatrix} R4 \\ R2 \\ Rg \\ R1 \\ R3 \\ = \end{bmatrix}$	M Eq- 1 M
	с	R1=R2 and R3=R4 What is Barkhausen's criteria? Which type of feedback is used in an oscillator? State types of oscillator. Barkhausen's Criteria - To obtain sustain oscillation the loop gain AB = 1 and phase shift of feedback signal should be 0° or 360° of an amplifier. it is called as barkshausen's criteria. Positive feedback is used for oscillator.	Criteria- 2 M Feedback type- 1M
		Types - RC oscillator LC Oscillator Define load regulation and line regulation	Osc. type- 1M
2	d	 Load Regulation Load regulation is the ability of the power supply to maintain its specified output voltage given changes in the load. This does not mean the tolerance applies when there are sudden changes in load, it means over the permissible load range the regulation can change by this amount. Line regulation Line regulation is the ability of the power supply to maintain its specified output voltage over changes in the input line voltage. It is expressed as percent of change in the output voltage relative to the change in the input line voltage. Sketch symbol and write truth table of: 	2 M each



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		i) AND gate ii) NAND gate	
	е	2-input AND gate NAND gate Input _A Output Input _B Output	
		A B Output 0 0 0 0 1 0 0 1 0 1 0 0 1 1 1	2 M each
		State function and application of robotic system	
		Function - To do the work that can substitute for humans and replicate human actions	
		Applicatios -	
	f	Military robots	Fun- 2 M
		Industrial robots	App- 2M
		Agriculture robots	
		Household robots	
		Medical robots	
		Nano robots	
		Swarm robots	
3		Attempt any four	16
	а	Pin Diagram of IC741 And Function of Each Pin	
		OFFSET NULL 1 8 NC INVERTING INPUT 2 7 V+ NON-INVERTING INPUT 3 6 OUTPUT V- 4 5 OFFSET NULL	02



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Pin No. 1 and pin no.5 (Offset Null)

Input offset voltage must be controlled so as to minimize offset. Offset voltage is nullify by application of a voltage of opposite polarity to the offset. An offset null-adjustment potentiometer may be used to compensate for offset voltage. The null-offset potentiometer also compensates for irregularities in the operational amplifier manufacturing process which may cause an offset. Consequently, the null potentiometer is recommended for critical applications.

Pin 2 (Inverted Input): All input signals at this pin will be inverted at output pin 6. Pins 2 and 3 are very important (obviously) to get the correct input signals or the op amp can not do its work.

Pin 3 (Non-Inverted Input): All input signals at this pin will be processed normally without invertion. The rest is the same as pin 2.

Pin 4 (-V): The V- pin (also referred to as Vss) is the negative supply voltage terminal. Supply-voltage operating range for the 741 is -4.5 volts (minimum) to -18 volts (max), and it is specified for operation between -5 and -15 Vdc. The device will operate essentially the same over this range of voltages without change in timing period.

Pin 6 (Output): Output signal's polarity will be the oposite of the input's when this signal is applied to the op-amp's inverting input. For example, a sine-wave at the inverting input will output a square-wave in the case of an inverting comparator circuit.

Pin 7 (+V): The V+ pin (also referred to as Vcc) is the positive supply voltage terminal of the 741 Op-Amp IC. Supply-voltage operating range for the 741 is +4.5 volts (minimum) to +18 volts (maximum), and it is specified for operation between +5 and +15 Vdc. The device will operate essentially the same over this range of voltages without change in timing period. Actually, the most significant operational difference is the output drive capability, which increases for both current and voltage range as the supply voltage is increased.

Pin 8 (N/C): The 'N/C' stands for 'Not Connected'. There is no other explanation. There is nothing connected to this pin, it is just there to make it a standard 8-pin package.

	b	Comparison of RC coupled Amplifier with Transformer Coupled Amplifier.	



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Coupling Resistor and Capacitor Transformer = 04 Distortion Less distortion More Distortion = 04 Voltage Less distortion More Distortion = 04 Applications For voltage Amplification For Power Amplification = 04 Any other suitable and relevant Applications may be consider. Full Wave Bridge Rectifier: Circuit diagram & input output waveform 02 Input output Waveforms Input output Waveforms Input output Waveforms 02		Parameter	RC Coupling	Transformer Coupling	01 *4
Distortion Less distortion More Distortion Voltage Less Voltage gain as compared do transformer coupled amplifier. More Voltage Gain Applications For voltage Amplification For Power Amplification Any other suitable and relevant Applications may be consider. Input output waveform Circuit Diagram:- C Full Wave Bridge Rectifier: Circuit diagram & input output waveform Circuit Diagram:- 02 Input output Waveforms Input output Waveforms 02			Resistor and Capacitor	Transformer	
Gain to transformer coupled amplifier. Applications For voltage Amplification Any other suitable and relevant Applications may be consider. c Full Wave Bridge Rectifier: Circuit diagram & input output waveform Circuit Diagram:- Circuit Diagram:- acc supply Implified to the suitable and the		Distortion	Less distortion	More Distortion	04
Any other suitable and relevant Applications may be consider. c Full Wave Bridge Rectifier: Circuit diagram & input output waveform Circuit Diagram:- Ac supply g f f f f f f f f f f f f f f f f f f			to transformer coupled	More Voltage Gain	
c Full Wave Bridge Rectifier: Circuit diagram & input output waveform Circuit Diagram:-		Applications	For voltage Amplification	For Power Amplification	
Circuit Diagram:- $ \begin{array}{c} $		Any other suit	able and relevant Applications m	ay be consider.	
02		Circuit Diagran	n:-	D ₄ L D ₃	02
d Bistable Multivibrator using IC555 and its waveform:-		νout			02
	d	Bistable Multi	vibrator using IC555 and its wave	eform:-	







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	all operation within PLC. The CPU makes dec on the program instruction in memory.	ision and executes control instructions based	02
	Input and output module		
	which is used to convert analog signal into d	utput devices and central processing unit (CPU)	
	Power supply		
		nit, input and output module unit. Power supply Most of the PLC operates on 0 volts DC and 24	
	Memory section		
	The memory section is the area of the CPU in retrieved. Data Memory is used to store nur code data etc. User memory contains user's	merical data required in math calculation, bar	
	Programming device		
	Programming devices are dedicated devices program memory or edit it and to monitor the also used to troubleshoot the PLC ladder log dedicated terminal or personal computer are of the PLCs.	ne execution of the program of the PLC. It is	
f	Comparison of Active and Passive Transduc	er	
	Active transducer	Passive transducer	
	The active transducer is also called as self-generating type transducer.	The passive transducer is also called as externally powered transducer.	
	The active transducer does not require any auxiliary (external) power supply.	The passive transducer requires auxiliary (external) power supply for transduction.	01*4=04
	The signal conversion is simpler.	The signal conversion is more complicated.	
	The energy required to produce output is obtained from the physical quantity.	They also derived part of the power required for conversion from physical quantity under measurement.	
1			1



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		· · · · · · · · · · · · · · · · · · ·	of passive transducer linear variable differential er).	
	It generates electric current or voltage directly in response to environmental stimulation.It gives a change in some passive electrical quantity, such as capacitance, resistance or inductance, as a result of stimulation.		quantity, such as certain cert	
		Any other suitable and relevant point may be considere	d.	
4		Attempt any Four		16
	a	Principle of R-2R type DAC and its Applications $ \frac{V_{ref} \rightarrow V_{ref}}{V_{ref} \rightarrow V_{ref}} \xrightarrow{R} \xrightarrow{R} \xrightarrow{R} \xrightarrow{R} \xrightarrow{R} \xrightarrow{R} \xrightarrow{R} $	e equivalent voltage is applied at and output is analog which is g applications and many more	02 (Circuit diagram is also expected)
		 Audio Amplifier Video Encoder Display Electronics Data Acquisition Systems 		Any two each of 01 Marks = 02
		Any other suitable and relevant application may a	also be considered.	
	b	Advance Vehicle Condition system (AVCS): General block principle of AVCS is expected. The students may explain the	-	



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 <u> </u>		1
	their logic or basic should be same. So depending upon diagram student should explain the	
	blocks.	
	One of the block diagram is shown below.	
	Triver Vehicle State Vehicle State Road State Uriver Vehicle State Vehicle State Vehicle State Vehicle State Vehicle State Vehicle State Vehicle State Vehicle State Vehicle State Vehicle State Vehicle State Vehicle Stability Controller Vehicle State Vehicle	02marks for BD and 02marksf or explanati on
С	 Features of 8085 Microprocessor. 1. It is 8 bit microprocessor. 2. It has 16 bit address line. 3. Memory capacity of 64KB. 4. Serial input output facility is available. 5. 256 I/O devices can be connected. 6. It requires only positive 5V supply. 7. DMA facility is also available. 8. Interrupt facility is available. Any other suitable and relevant feature may also be considered. 	Min. 8 features 0.5*8=04
d	Data Logger and its application A data logger or data recorder is an electronic device that records data over time or in relation to location either with a built in instrument or sensor or via external instruments and sensors. Increasingly, but not entirely, they are based on a digital processor (or computer). Applications:-	02 + 02 (min. 2 applicati ons)
	Applications.ManufacturingFood processingGeneral researchMonitoring in buildingsAutomotivePublic utilitiesCivil engineeringEnvironmental monitoring	=04



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	1					1
		Rectification				02
			-		carries out the rectification	
		•	•	-	ating voltage or current into	
		corresponding direct (DC) quantity. The input	to a rectifier	is ac whereas its output is	
		unidirectional pulsating	DC. Usually a full wave re	ctifier or a bri	dge rectifier is used to rectify	
		both the half cycles of t	he ac supply (full wave red	ctification).		
		DC Filter				
		The rectified voltage f	rom the rectifier is a pul	sating DC vol	tage having very high ripple	
		content. But this is not we want, we want a pure ripple free DC waveform. Hence a filter is				
		used. Different types of	filters are used such as ca	pacitor filter,	LC filter, Choke input filter, π	
		type filter.				
		Regulation				
		•	n a regulated DC power s	supply. The o	utput voltage or current will	
			•		ic mains or due to change in	
					or due to other factors like	
					g a regulator. A regulator will	
					or any other changes occur.	
		•	-	•	a zener diode operated in the	
		-		-	like 78XX and 79XX are used	
		-	s of voltages at the output			
05		Attempt any four		•		02 Marks
	a)	Ac signal conditioning :	Ac Signal conditioning is	the manipulat	ion of a signal from a sensor	
		or transducer in a way the	hat prepares it for the next	stage of proce	essing. It includes	
		amplification, modulation	on, sampling, filtering etc.			
		T				02 Marks
		• =	in AC signal Conditionin zeroing network (offset nu	•	t)	
		b) AC amplifier	zeronig network (oriset nu	ini ying circui	()	
		c) Phase detector				
		d) Low pass filter				
		e) Power supply				
	b)	Transistor as switch				02 Marks
			h			
		Case I: When Vin =0 then base current of transistor will be zero hence collector current is				
		zero. Transistor is in cutoff region. which indicates that the switch is OFF.				
		Case II: When positive	Vin is applied then base ar	d collector cu	rrent flows through the	
		circuit. Transistor is in saturation region which indicates that the Switch is ON.				
		Off switch				
		Output				01 Mark
		Output				
		L	On Switch			







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	Explanation:		
	- Single channel data acquisition system is used to convert only single physical quantity into it equivalent digital form	02 Marks	
- It consists of transducer, signal conditioner, sample & hold circuit and ADC.			
	- Transducer: It converts physical quantity into analog electrical signal.		
	- Signal conditioner: Analog electrical signal is processed & boost by this circuit.		
	- Sample & Hold circuit: It samples the analog signal at regular interval and converts it into discrete signal.		
	- ADC: It is used to convert each sampled value into equivalent digital signal.		
e)	Opto coupler : optocoupler, photocoupler, or optical isolator, is a component that transfers electrical signals between two isolated circuits by using light.	01 Mark	
		01 Mark	
	Advantages:		
	- Control circuits are well protected due to electrical isolation.	(Any 2)	
	 Wideband signal transmission is possible. Due to unidirectional signal transfer, noise from the output side does not get coupled to the input side. Interfacing with logic circuits is easily possible. 	02 Marks	
f)	- It is small size & light weight device. Decade counter using T flipflop	02 marks	
	Logic 1 Logic 1 Logic 1 Logic 1 T _A Q _A Flip-flop A CLR Q _B CLR Q _C CLR Q _C CLR Q CLR CLR C CLR C CLR C CLR C CLR C C		



Sut	oject Name:	BEM		<u>Model /</u>	<u>Answer</u>	2	Subject C	ode: 17302	
		Clo	Clock Count	(Output b	Decimal			
		Со		QD	QC	QB	QA	Value	

			Count	QD	QC	QB	QA	Value			
			1	0	0	0	0	0		02 marks	
			2	0	0	0	1	1			
			3	0	0	1	0	2			
			4	0	0	1	1	3			
			5	0	1	0	0	4			
			6	0	1	0	1	5			
			7	0	1	1	0	6			
			8	0	1	1	1	7			
			9	1	0	0	0	8			
			10	1	0	0	1	9			
			11	Count	ter Reset	s its Out	puts bac	k to Zero			
6	a)	Decoder : It is	a combinatio	on logic c	ircuit use	uit used to select a device or decode. Decoders					
		consist of numb	er of inputs	(N) and r	number of	f output(N	(I) and bo	th are related	l as $2^{N} >=$		
		M The standard	decoders are	e 1:2,2:4,	3:8 and so	o on					
		Truth Table					1			02 Mark	
					Dage 17	-{ 20					



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			Inp	uts					Out	puts						
		EN	Α	В	С	Y ₇	Y ₆	Y ₅	Y ₄	Y ₃	Y ₂	Y ₁	Y ₀			
		0	×	×	×	0	0	0	0	0	0	0	0			
		1	0	0	0	0	0	0	0	0	0	0	1			
		1	0	0	1	0	0	0	0	0	0	1	0			
		1	0	1	0	0	0	0	0	0	1	0	0			
		1	0	1	1	0	0	0	0	1	0	0	0			
		1	1	0	0	0	0	0	1	0	0	0	0			
		1	1	0	1	0	0	1	0	0	0	0	0			01 mark
		1	1	1	0	0	1	0	0	0	0	0	0			
 		1	1	1	1	1	0	0	0	0	0	0	0			
b)	a) Typ							NY 4	4)							01 mark for each
	b) Nu				-	-		C								correct
			-			-			range							answer
	_	c) Operating voltage and operating current ranged) Scan time of PLC														
	d) Scan time of PLCe) Memory size of PLC															
	f) Typ			-		,										
	g) Typ				ng											
	h) Rel															
	i) Flez	xibili	ty of :	PLC												
c)									Rin		_		Ic	_		
	CB CON	FIGU	RAT	ION	OF I	RIT	_		-	∿		\sim		· · ·	_	02 Marks
				1011		JJ I	Î		IE	•	(\	_()		⊾ ∕ 1		
							Vin	\Diamond			\mathbf{n}	Б		^R -≥	Vout	
								Ť			IB↓			1		
							_		+	-		+		- +	_	
									V	BE	닅	F	VBC	- I _C		
										Rin	в (P	\prec			
					OF		-	1			(L.			+ <u> </u>	Œ
	CE CON	FIGU	KAI	10N	OF I	SJT	Vin			в				†	- – *	¢E
									V			IE		Vout		
							-	↓		+ ⊢			<u>+</u>	+		02 Marks
<u> </u>							Da	ge 18	of 20	VBE			_			



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d)					02 Marks							
	J CLK K		Q Q Q									
	Race around condition											
	- Race around condition occurs when all inputs of J-K flip flop are 1 (J=K=CLK=1).											
	- J-K flip flop keep toggling indefinitely as long as J=K=CLK=1 and that condition is known as race around condition.											
	Truth Table											
	JK											
	0 0	t Q ₀ (no cha	inge)									
	0 1	t o										
	1 1	↑ Q ₀ (toggl	es)									
e)	Compare full wave rectifier and half wave rectifier											
	Parameters	Half-Wave Rectifiers	Full-Wave Rectifiers		for each correct point							
	Number of diodes	Only 1	2 or 4									
	Output Voltage	Available only for half cycle of AC input	Available for both cycle of AC input									
	Ripple Factor	1.21	0.482									
	Rectification Efficiency	40.6%	81.2%									
f)	The output of a flip flop	can be changed by	bring a small change i	n the input signal. This	02 Marks							

