



MAHARASHTRA STATE BOARD OF TECHNICAL EDUCATION
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WINTER – 2016 EXAMINATION

Model Answer

Subject Code: 17510

Important Instructions to examiners:

- 1) The answers should be examined by key words and not as word-to-word as given in the model answer scheme.
- 2) The model answer and the answer written by candidate may vary but the examiner may try to assess the understanding level of the candidate.
- 3) The language errors such as grammatical, spelling errors should not be given more Importance (Not applicable for subject English and Communication Skills).
- 4) While assessing figures, examiner may give credit for principal components indicated in the figure. The figures drawn by candidate and model answer may vary. The examiner may give credit for any equivalent figure drawn.
- 5) Credits may be given step wise for numerical problems. In some cases, the assumed constant values may vary and there may be some difference in the candidate's answers and model answer.
- 6) In case of some questions credit may be given by judgement on part of examiner of relevant answer based on candidate's understanding.
- 7) For programming language papers, credit may be given to any other program based on equivalent concept.

Q. No.	Sub Q.N.	Answer	Marking Scheme
1.	A) a) Ans.	Attempt any three of the following: Draw a basic structure of power system showing different voltage levels.	12 4M



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WINTER – 2016 EXAMINATION

Model Answer

Subject Code: 17510

		<p>2M voltage levels</p> <p>2M line diagram</p>
<p>b)</p> <p>Ans.</p>	<p>Give the expression for complex power, active power and reactive power at receiving end.</p> <p>Complex power at the receiving end is given by</p> $S_R = V_R I_R^* \dots\dots\dots$ $P_R = \frac{ V_S V_R }{ B } \cos(\beta - \delta) - \frac{ A V_R ^2}{ B } \cos(\beta - \delta) \dots\dots$ $Q_R = \frac{ V_S V_R }{ B } \sin(\beta - \delta) - \frac{ A V_R ^2}{ B } \sin(\beta - \delta) \dots$ <p>Where P_R= Real or active power in MW, Q_R= Reactive power in MVAR</p> <p>V_S = Sending end voltage per phase in KV</p> <p>V_R = Receiving end voltage per phase in KV</p> <p>δ = Power angle</p> <p>A, B = Generalized Circuit Constant</p>	<p>4M</p> <p>1M</p> <p>1M</p> <p>1M</p> <p>1M</p>



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c)	<p>State the significance of resistance parameter on performance of transmission line.</p> <p>Ans. Significance of resistance:</p> <ol style="list-style-type: none"> 1. Resistance causes voltage drop IR 2. Voltage drop in transmission line affects regulation 3. Resistance causes I²R losses, which affects efficiency. 4. Temperature of line increases due to resistance. 	<p>4M</p> <p><i>1M for each point</i></p>
d)	<p>List the advantages of generalised circuit representation.</p> <p>Ans. Advantages of generalized:</p> <ol style="list-style-type: none"> 1. The generalized circuit equations are well suited to transmission lines. Hence for given any type of the transmission line (short, medium, long). The equation can be written by knowing the values of A B C D constants. 2. Just by knowing the total impedance and total admittance of the line the values of A B C D constants can be calculated. 3. By using the generalized circuit equations VRNL $V_S = AV_R + BI_R$ i.e. when $IR = 0$ $VRNL = V_S / A$ Now the regulation of the line can be immediately calculated by $\% \text{ Voltage Regulation} = V_S / A - V_R / V_R \times 100$ 4. Output power = $V_R I_R \cos \phi_R$ for1ϕ...ckt. $= 3V_R I_R \cos \phi_R$ for3ϕ.....ckt. <p style="margin-left: 40px;">Input power = $V_S I_S \cos \phi_S$.....1ϕ..ckt. $= 3 V_S I_S \cos \phi_S$3ϕ..ckt.</p> <p>losses in the line = input – output 5. By calculating input and output power efficiency can be calculated. 6. Series circuit : When two lines are connected such that the output of the first line serves as output to the second line and the output of the second line is fed to the load, the two lines behave as to parts networks in cascade. Its ABCD constants can be obtain by using following matrix: </p> $\begin{vmatrix} A & B \\ C & D \end{vmatrix} = \begin{vmatrix} A_1 & B_1 \\ C_1 & D_1 \end{vmatrix} \times \begin{vmatrix} A_2 & B_2 \\ C_2 & D_2 \end{vmatrix}$	<p>4M</p> <p><i>Any 4 advantages 1M each</i></p>



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		<p>or $B = AZ_{rs} = Z_{rs} \sqrt{\frac{Z_{so}}{Z_{ro} - Z_{rs}}}$ -----(b)</p> <p style="text-align: center;">$Z_{so} = \frac{A}{C}$</p> <p>$\therefore C = \frac{A}{Z_{so}} = \frac{1}{Z_{so}} \sqrt{\frac{Z_{so}}{Z_{ro} - Z_{rs}}}$ -----(c)</p> <p style="text-align: center;">$Z_{ro} = \frac{D}{C}$</p> <p>$\therefore D = C \cdot Z_{ro} = \frac{Z_{ro}}{Z_{so}} \sqrt{\frac{Z_{so}}{Z_{ro} - Z_{rs}}}$</p> <p>$= Z_{ro} \sqrt{\frac{1}{(Z_{ro} - Z_{rs})Z_{so}}}$ -----(d)</p> <p>If $Z_{ro} = Z_{so}$ we get $A = D$ for symmetric network</p>	1M
	<p>b)</p> <p>Ans.</p>	<p>Define skin effect and proximity effect. State factors on which skin effect and proximity effect depends.</p> <p>SKIN EFFECT:</p> <div style="text-align: center;"> </div> <p>The distribution of current throughout the cross section of a conductor is uniform when DC is passing through it. But when AC is flowing through a conductor, the current is non-uniformly distributed over the cross section in a manner that the current density is higher at the surface of the conductor compared to the current density at its center. This phenomenon is called skin effect.</p> <p>Skin effect depends on factors:</p> <ul style="list-style-type: none"> • Current • Permeability of material • Frequency • Conductor diameter • Diameter • Material of conductor <p>PROXIMITY EFFECT:</p> <p>When the alternating current is flowing through a conductor alternating magnetic flux is generate surrounding the conductor. This</p>	<p>6M</p> <p style="margin-top: 100px;">2M</p> <p style="margin-top: 100px;">Any 2, ½ M for each</p>



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		<p>magnetic flux associates with the neighboring conductor and generate circulating currents. This circulating currents increases resistance of conductor. This phenomenon is called as, “proximity effect”.</p> <p>Factors affecting proximity effect:</p> <ol style="list-style-type: none"> 1. Conductor size (diameter of conductor) 2. Frequency of supply current. 3. Distance between conductors. 4. Permeability of conductor material 	<p>2M</p> <p><i>Any 2, 1/2 M for each</i></p>
2.	<p>a) i) Ans.</p>	<p>Attempt any two of the following:</p> <p>Define generalised circuit and generalised circuit constant.</p> <p>Generalized Circuit: An passive, linear, bilateral network with two port terminals is known as generalized circuit. A transmission line is a 2 port network, two input terminals where power enters & two output terminals where power leaves the network.</p> <div style="text-align: center;"> </div> <p>Generalized Circuit Constant:</p> <ol style="list-style-type: none"> 1) $A = \frac{V_S}{V_R}; I_R = 0$ It is the ratio of the voltage impressed at the sending end to the voltage at the receiving end when the receiving end is open circuited. It is a dimension less quantity. 2) $B = \frac{V_S}{I_R}; V_R = 0$ It is the volt impressed at the sending end to current of receiving end when receiving end is short circuited. It is known as Transfer impedance. Its unit is in ohms. 3) $C = \frac{I_S}{V_R}; I_R = 0$ It is defined as the ratio sending end current to the receiving end voltage when receiving end is open circuited. It is known as Transfer admittance and its unit mho. 4) $D = \frac{I_S}{I_R}; V_R = 0$ 	<p>16 4M</p> <p><i>Definitio n of generali sed circuit 1M</i></p> <p><i>Generali sation circuit constant 3M</i></p>

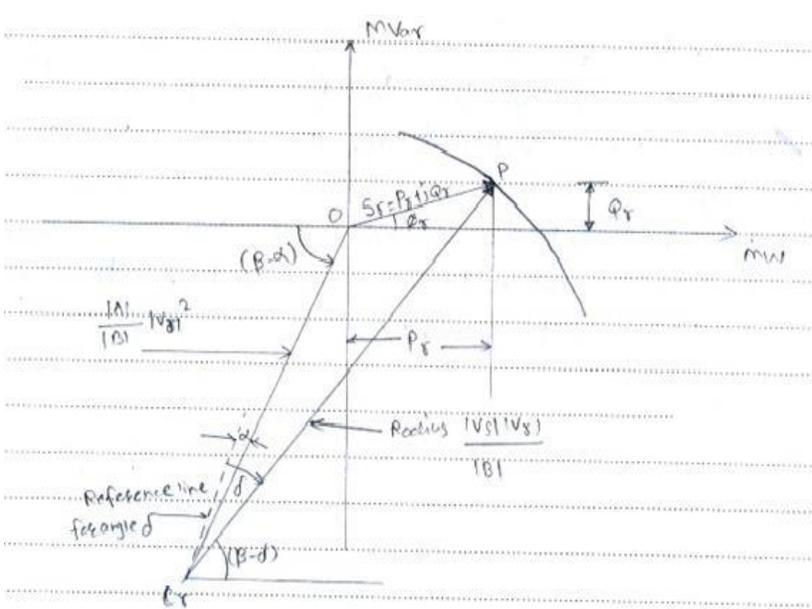
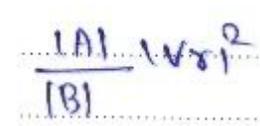


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Model Answer

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		<p>It is the ratio of amperes impressed at the sending end to the ampere at the receiving end when the receiving end is short circuited. It is a pure quantity.</p>	
<p>ii) Ans.</p>		<p>Explain the procedure for receiving end circle diagram with usual notation.</p>  <p>$S_r = \frac{- A V_B ^2}{ B } \angle(\beta-\alpha) + \frac{ V_s V_r }{ B } \angle(\beta-\delta)$</p> <p>Step-1: Draw the X-Y plane in which plane X represents the active power (MW) & axis-y-represents the Reactive power (MVA).</p>  <p>Step-2: To draw the center of the circle take the distance equal to $\frac{ A V_B ^2}{ B }$ & angle equal to $(\beta-\alpha)$ & draw the line in third quadrant & locate the point 'n'.</p> <p>Step-3: To draw the circle the radius is taken equal to $V_s V_r$ & draw a circle in 1st quadrant.</p>	<p align="right">4M</p> <p align="right">Diagram 2M</p> <p align="right">Explana tion 2M</p>



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		<p>Step-4: The operating point p on the circle is located by the amount of real power delivered to the load i.e. P_r</p> <p>Step-5: Joint the 'op' & draw the line parallel from point P to Y-axis. 'op' represents the true power $S_r = P_r + jQ_r$ & the corresponding value of Q_r can be read from the diagram.</p> <p>Step-6: Draw the reference line w.r.t. 'on' at an angle α. The power angle is the angle between the ref. line shown & phasor 'np'.</p>	
2.	b)	<p>Determine inductive reactance of 1 ϕ tr. Line arrangement shown in fig.1 per mt. length. The dia. of each conductor is 1cm and current is equally shared by two parallel conductors.</p> <p>$d(aa') = 25\text{ cm}$</p>	8M
	Ans.		



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		$d = 1 \text{ cm} \quad \therefore r = 0.5 \text{ cm} = 0.5 \times 10^{-2} \text{ m}$ $\frac{L}{M} = 2 \times 10^{-7} \ln \frac{D_m}{D_s}$ $\text{Self GMR} = 0.7788 r$ $= 0.7788 \times 0.5 \times 10^{-2}$ $= 3.894 \times 10^{-3} \text{ — 2 mark}$ $\therefore D_{aa} = D_{a'a'} = D_{bb} = D_{b'b'} = 3.894 \times 10^{-3} \text{ GMR}$ $\therefore D_g = (D_{aa} \times D_{a'a'} \times D_{bb} \times D_{b'b'})^{1/4}$ $= (3.894 \times 10^{-3} \times 3.894 \times 10^{-3} \times 0.25 \times 0.25)^{1/4}$ $= (3.894 \times 10^{-3} \times 0.25)^{1/2}$ $= 0.0312 \text{ m. — 2 mark}$ $D_m = (D_{ab} \times D_{ab'} \times D_{a'b} \times D_{a'b'})^{1/4}$ $= (0.75 \times 1.0 \times 0.5 \times 0.75)^{1/4}$ $= (0.281)^{1/4}$ $= 0.728 \text{ m. — 2 mark}$ $\frac{L}{M} = 2 \times 10^{-7} \ln \frac{D_m}{D_s}$ $= 2 \times 10^{-7} \ln \frac{0.728}{0.0312}$ $= 6.299 \times 10^{-7}$ $\frac{L}{\text{km}} = 6.299 \times 10^{-7} \times 1000$ $= 629.9 \times 10^{-6} \text{ H — 1 mark}$ $\therefore X_L = 2\pi f L = 2 \times 3.14 \times 50 \times 629.9 \times 10^{-6}$ $= 0.1977 \text{ } \Omega / \text{km — 1 mark}$	
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2.	c)	<p>If A and B constants of a 3 ϕ tr. Line are $0.9 \angle 1^\circ$ and $100 \angle 85^\circ$ respectively. Determine the receiving end current and power supplied to load. Assume both sending end and receiving end voltages are 200 kV with phase diff. of 8° between them.</p> <p style="margin-left: 20px;">Ans.</p> $A = 0.9 \angle 1^\circ \quad \delta = 8^\circ$ $B = 100 \angle 85^\circ$ $ V_S = V_R = \frac{200}{\sqrt{3}} \text{ kV} \quad \text{--- 1 mark}$ $\text{Now } V_S = AV_R + BI_R \quad \text{--- 1 mark}$ $I_R = \frac{V_S}{B} - \frac{AV_R}{B} \quad \text{--- 1 mark}$ $I_R = \frac{200 \times 10^3 \angle 8^\circ}{\sqrt{3} \cdot 100 \angle 85^\circ} - \frac{0.9 \angle 1^\circ \times 200 \times 10^3 \angle 0^\circ}{\sqrt{3} \cdot 100 \angle 85^\circ}$ $= 1154.70 \angle -77^\circ - 1039.23 \angle -84^\circ$ $I_R = 259.75 - j1125.10 - 108.62 + j1033.53$ $= 151.13 - j91.57$ $= 176.70 \angle -31.21^\circ \quad \text{--- 2 marks}$ $3\phi S_R = \frac{V_S V_R}{B} \angle \beta - \delta - \frac{AV_R^2}{B} \angle \beta - \gamma \quad \text{--- 1 mark}$ $= \frac{200 \times 200}{100} \angle 85 - 8 - \frac{0.9 \times 200^2}{100} \angle 85 - 1$ $= 400 \angle 77^\circ - 360 \angle 84^\circ$ $P_R = 400 \cos 77^\circ - 360 \cos 84^\circ$ $= 89.98 - 37.63$ $= 52.345 \text{ MW} \quad \text{--- 2 mark}$	8M
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3.	a)	<p>Attempt any four of the following: Draw the reactance diagram of given power system as shown in fig.2 select generator rating as the common base value.</p> <div style="text-align: center;"> <p style="text-align: center;">Fig. 2</p> </div> <p>Ans.</p> <p>Assuming Gen as base \therefore Base MVA = 20 Base V = 11 kV for Gen. side = 110 kV for Tr. line side & 11 kV for motor side</p> <p>Calculation of Xpu \rightarrow</p> <ol style="list-style-type: none"> ① Generator $\rightarrow X_{pu\ new} = X_{pu\ old} = \underline{0.1\ pu}$ ② Transformer T₁ & T₂ $X_{pu\ new} = X_{pu\ old} \times \frac{MVA_{new}}{MVA_{old}} \times \left(\frac{kV_{old}}{kV_{new}}\right)^2$ $= 0.08 \times \frac{20}{25} \times \left(\frac{11}{11}\right)^2 = \underline{0.064\ pu}$ ③ Motor $X_{pu\ new} = 0.1 \times \frac{20}{10} \times \left(\frac{11}{11}\right)^2 = \underline{0.2\ pu}$ ④ Tr. line - $X_{pu} = \frac{X_{actual}}{X_{Base}} = X_{actual} \times \frac{MVA_{Base}}{(kV_{Base})^2}$ $= 80 \times \frac{20}{(110)^2} = \underline{0.1322\ pu}$ <div style="text-align: center;"> </div>	16 4M
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	<p>around its periphery and length.</p> <p>Consider the conductor ‘a’ alone with the charge and ‘b’ without any charge. Now the p. d between the conductors a & b is</p> $\vartheta_{ab} = \frac{q_a}{2\pi k} \log_e \frac{D}{r_a} \quad \text{--- v/mt - (1)}$ <p>Similarly consider b with charge and ‘a’ without any charge. Then the p. d. between the conductors b & a is given by</p> $\vartheta_{ba} = \frac{q_b}{2\pi k} \log_e \frac{D}{r_b} \text{---(2)}$ <p>p. d. between a & b can be written as,</p> $\vartheta_{ab} = -\vartheta_{ba} = \frac{-q_b}{2\pi k} \log_e \frac{D}{r_b} \text{---(3)}$ <p>Now by super position theorem, the net p. d. between a & b when both the conductors are charged equally oppositely can be written by adding the eq. ----- (1) & (3)</p> $\vartheta_{ab} = \vartheta_{ab}' + \vartheta_{ab}''$ $= \frac{q_a}{2\pi k} \log_e \frac{D}{r_a} - \frac{q_b}{2\pi k} \log_e \frac{D}{r_b}$ $= \frac{q_a}{2\pi k} \log_e \frac{D}{r_a} + \frac{q_b}{2\pi k} \log_e \frac{D}{r_b}$ <p>Since $q_a = -q_b$</p> $= \frac{q_a}{2\pi k} \left[\log_e \frac{D}{r_a} + \log_e \frac{D}{r_b} \right]$ $= \frac{q_a}{2\pi k} \log_e \frac{D^2}{r_a r_b}$ <p>If $r_a = r_b = r$</p> $\vartheta = \frac{q_a}{2\pi k} \log_e \frac{D^2}{r^2}$ $= \frac{2q_a}{2\pi k} \log_e \frac{D}{r}$ $\vartheta = \frac{q_a}{\pi k} \log_e \frac{D}{r} \quad \text{-----v/mt.(4)}$ <p>Capacitance between two conductors i.e. line capacitance Can be written as—</p> $C_{ab} = \frac{q_a}{V_{ab}} = \frac{\pi k}{\log_e D/r} \quad \text{-----F/Mt.(5)}$ <p>And it is represented as</p>	
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4.	<p>A) a) Ans.</p>	<p>Attempt any three of the following:</p> <p>Define self GMD and mutual GMD.</p> <p>Mutual GMD: If conductor A has 'n' no of sub conductor & conductor B has 'm' no of subconductor, then <i>m</i>th root of the <i>mn</i> terms, which are the products of all possible mutual distances from the n filaments of conductor A to m' filaments of conductor B. It is called <i>mutual geometric mean distance</i> (mutual GMD between conductor A and B and abbreviated as D_m.</p> <p>Similarly,</p> <p>Self GMD: or GMR n^2th root of n^2 product terms (n sets of n product terms each). Each set of n product term pertains to a filament and consist of r' (D_{ii}) for that filament and $(n - 1)$ distances from that filament to every other filament in conductor A. It is defined as the <i>self-geometric</i> meandistance (self GMD) of conductor A, and is abbreviated as D_{SA}. Sometimes, self GMD is also called <i>geometric mean radius</i> (GMR).</p> <p>Example let radius of conductor X & Y is = r</p> <div style="text-align: center;"> </div> <p>Self GMD of conductor X = $\sqrt[4]{D_{11}D_{1'1'}D_{11'}D_{1'1}} = \sqrt[4]{r'x r'x d x d} = \sqrt{r'xd}$</p> <p>Self GMD of conductor Y = r'</p> <p>Mutual GMD between conductor X & Y = $\sqrt{D_{12}D_{1'2}} = \sqrt{\left(\frac{d}{2} + D\right) x \left(D - \frac{d}{2}\right)}$</p>	<p>12 4M</p> <p>2M each</p>



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Model Answer

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		<p>If $Q_s = Q_r$ ---- V_r flat cha So to maintain balance in Q_s & Q_r Reactive power compensation is required.</p> <p>Devices for of Reactive power compensation:</p> <ol style="list-style-type: none"> 1) shunt capacitor bank –substation & medium Tr. line 2) Inductance reactor bank- long HV tr. line 3) Syn. condenser- load centre 4) Auto transformer – substations 	<p><i>Devices for of reactive power compens ation</i></p> <p>2M</p>
4.	B) a)	<p>Attempt any one of the following:</p> <p>A 50Hz 3 ϕ tr. line is 250 km long. It has a total series impedance of $35 + j40 \Omega$ and shunt admittance of $930 \times 10^{-4} \Omega$. It delivers 40,000 kW with 90% p.f. lag. Find ABCD constant considering medium line having nominal T circuit regulation of line.</p>	6 6M
	Ans.	<p>$Z = 35 + j40$ $Y = 930 \times 10^{-4} \text{ pu}$</p> <p>$I_R = \frac{40000}{\sqrt{3} \times 220 \times 0.9} = 342.95 \text{ Amp } \angle -25.84^\circ$</p> <p>ABCD constant for T ckt.</p> <p>$A = (1 + \frac{YZ}{2}) = 1 + \frac{(930 \times 10^{-4} / 90)(35 + j40)}{2}$</p> <p style="margin-left: 40px;">$= 1 + (0 - 1.85 + j1.627)$</p> <p style="margin-left: 40px;">$= 1.84 \angle 117.85^\circ = D \rightarrow (1M)$</p> <p>$B = Z (1 + \frac{YZ}{4}) = (35 + j40) (1 + \frac{930 \times 10^{-4} / 90 \times (35 + j40)}{4})$</p> <p style="margin-left: 40px;">$= 43.41 \angle 133.89^\circ \rightarrow (1M)$</p> <p>$C = Y = 930 \times 10^{-4} / 90 \rightarrow (1M)$</p> <p>$V_s = A V_R + B I_R$</p> <p style="margin-left: 40px;">$= 1.84 \angle 117^\circ \times \frac{220 \times 10^3}{\sqrt{3}} + 43.41 \angle 133.89^\circ \times 342.95 \angle -25.84^\circ$</p> <p style="margin-left: 40px;">$= 248,428.38 \angle 116.46^\circ$</p> <p style="margin-left: 40px;">$= 248.42 \text{ kV} \rightarrow (2M)$</p> <p>$\% \text{ Reg} = \frac{\frac{V_s}{A} - V_R}{V_R} \times 100$</p> <p style="margin-left: 40px;">$= \frac{\frac{248.42}{1.84} - 220/\sqrt{3}}{220/\sqrt{3}} \times 100 = 6.29\%$</p> <p style="text-align: right; margin-right: 20px;">(1M)</p>	



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b)	<p>Find self GMD for arrangement as shown in fig.3 If $r = 0.1\text{cm}$.</p> <div style="text-align: center;"> <p>Fig. 3</p> </div> <p>Self GMD if $r = 0.1\text{cm}$</p> <div style="display: flex; align-items: flex-start;"> <div style="margin-right: 20px;"> </div> <div> $D_s = \sqrt[9]{(D_{11} D_{12} D_{13}) (D_{21} D_{22} D_{23}) (D_{31} D_{32} D_{33})}$ $= \sqrt[9]{(D_{11} D_{12} D_{13})^2 (D_{21} D_{22} D_{23})} \quad \rightarrow (1M)$ $= \sqrt[9]{(0.7788r + 2r \times 4r)^2 (2r \times 0.7788r \times 2r)}$ $= \sqrt[9]{r^9} \sqrt[9]{120.92} \quad \rightarrow (1M)$ $= 1.70r = \underline{0.17\text{cm}} \quad \rightarrow (1M)$ </div> </div> <div style="display: flex; align-items: flex-start;"> <div style="margin-right: 20px;"> </div> <div> $D_{14} = \sqrt{(4r)^2 - (2r)^2} = \sqrt{2} r$ $D_s = \sqrt[36]{(D_{11} D_{12} D_{13} D_{14} D_{15} D_{16})^3 (D_{21} D_{22} \dots D_{23} D_{24} D_{25} D_{26})^3}$ $\rightarrow (1M)$ $D_s = \sqrt[12]{(D_{11} D_{12} D_{13} D_{14} D_{15} D_{16}) (D_{21} D_{22} D_{23} D_{24} D_{25} D_{26})}$ $= \sqrt[12]{(0.7788r \times 2r \times 4r \times \sqrt{2}r \times 4r \times 2r) (2r \times 0.7788r \times 2r \times 2r \times \sqrt{2}r \times 2r)}$ $\rightarrow (1M)$ $= 2.102r = \underline{0.210\text{cm}} \quad \rightarrow (1M)$ </div> </div>	6M
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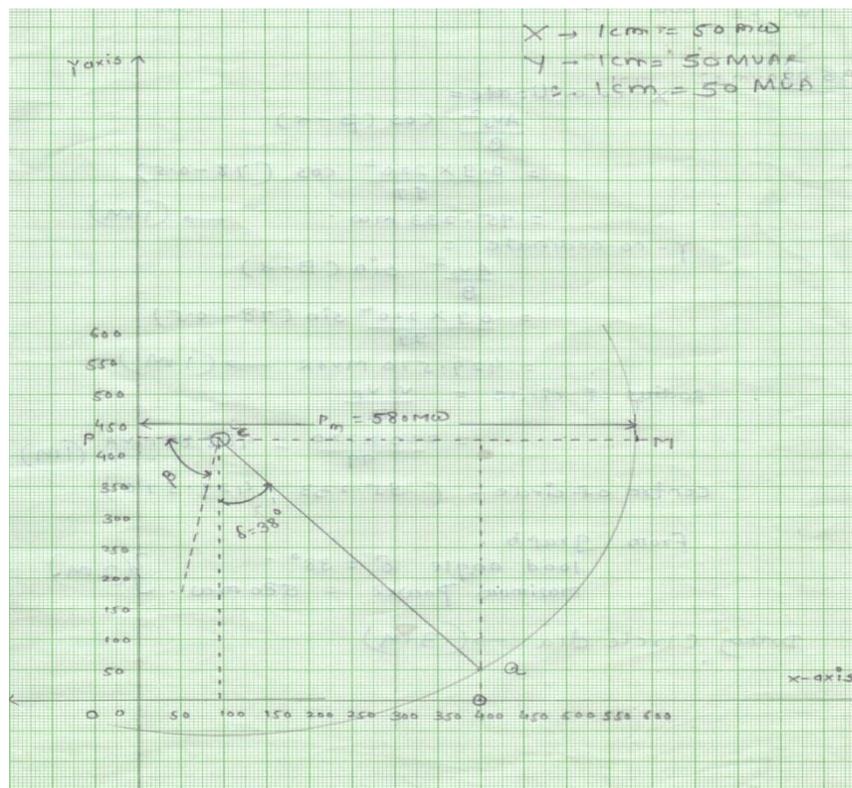
Model Answer

Subject Code: 17510

$$\begin{aligned} X\text{-co-ordinate} &= \frac{AV_s^2}{B} \cos(\beta - \alpha) \\ &= \frac{0.9 \times 220^2}{99} \cos(78 - 0.5) \\ &= 95.233 \text{ MW} \rightarrow (1M) \\ Y\text{-co-ordinate} &= \frac{AV_s^2}{B} \sin(\beta - \alpha) \\ &= \frac{0.9 \times 220^2}{99} \sin(78 - 0.5) \\ &= 429.570 \text{ MVAR} \rightarrow (1M) \\ \text{Radius of circle} &= \frac{V_s V_R}{B} \\ &= \frac{220 \times 220}{99} = 488.88 \text{ MVA} \rightarrow (1M) \\ \text{Centre of circle} &= (95.233, 429.570) \end{aligned}$$

From graph.
load angle $\delta = 38^\circ$
Maximum Power = 580 MW. } (2M)

Draw circle dia \rightarrow (3M)





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WINTER – 2016 EXAMINATION

Model Answer

Subject Code: 17510

	<p>c)</p> <p>Ans.</p>	<p>A 3 ϕ line with equilateral spacing 3mt is to be rebuilt with horizontal spacing as $D_{13} = 2D_{12} = 2D_{23}$. The conductors are to be fully transposed. Find the spacing between adjacent conductors such that new line has the same inductance as original value.</p> <p>3 phase line with equilateral spacing</p> $L = 2 \times 10^{-7} \log_e \frac{D}{r'} = 2 \times 10^{-7} \log_e \frac{3}{r'} \quad \text{-----Eq 1}$ <p>With horizontal spacing</p> $2 \times 10^{-7} \log_e \frac{D_{eq}}{r'} \quad \text{---eq 2}$ $D_{eq} = \sqrt[3]{D_{12} \times D_{23} \times D_{31}}$ <p>Inductance L remains same Equating eq 1 & eq 2</p> $L = 2 \times 10^{-7} \log_e \frac{D}{r'} = 2 \times 10^{-7} \log_e \frac{D_{eq}}{r'} \quad \text{.....}$ $\frac{D}{r'} = \frac{D_{eq}}{r'}$ $D = D_{eq} = \sqrt[3]{(D_{12} \times D_{23} \times D_{31})}$ $3 = \sqrt[3]{((D_{12})^2 \times (2D_{12}))}$ $3 = \sqrt[3]{2 \times (D_{12})^3}$ $D_{12} = \frac{3}{\sqrt[3]{2}} = 2.381 \text{ m} \quad \text{.....}$	<p>8M</p> <p>1M</p> <p>1M</p> <p>3M</p> <p>3M</p>
6.	<p>a)</p> <p>Ans.</p>	<p>Attempt any four of the following:</p> <p>Prove that complex power in power system is $S = VI^*$.</p>	<p>16</p> <p>4M</p>



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WINTER – 2016 EXAMINATION

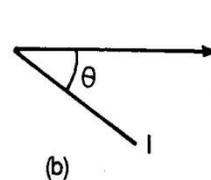
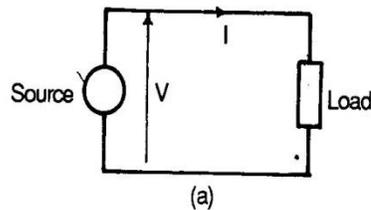
Model Answer

Subject Code: 17510

Consider a single-phase load fed from a source as in Fig. . Let

$$V = |V| \angle \delta$$

$$I = |I| \angle (\delta - \theta)$$



Complex power flow in a single-phase load

When θ is positive, the current lags behind voltage. This is a convenient choice of sign of θ in power systems where loads have mostly lagging power factors.

4M

Complex power flow in the direction of current indicated is given by

$$S = VI^*$$

$$= |V| |I| \angle \theta$$

$$= |V| |I| \cos \theta + j |V| |I| \sin \theta = P + jQ$$

or

$$|S| = (P^2 + Q^2)^{1/2}$$

Here

S = complex power (VA, kVA, MVA)

$|S|$ = apparent power (VA, kVA, MVA); it signifies rating of equipments (generators, transformers)

$P = |V| |I| \cos \theta$ = real (active) power (watts, kW, MW)

$Q = |V| |I| \sin \theta$ = reactive power

= voltamperes reactive (VAR)

= kilovoltamperes reactive (kVAR)

= megavoltamperes reactive (MVAR)

It immediately follows from Eq. that Q , the reactive power, is positive for lagging current (lagging power factor load) and negative for leading current (leading power factor load). With the direction of current indicated in Fig. $S = P + jQ$ is supplied by the source and is absorbed by the load.



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WINTER – 2016 EXAMINATION

Model Answer

Subject Code: 17510

		<p>$\theta = \tan^{-1} \frac{Q}{P} =$ positive for lagging current = negative for leading current</p> <p>Phasor representation of complex power (lagging pf load)</p> <p>In Electrical engineering $S=P+jQ$. Where Q is positive and it is inductive reactive power which lags i.e. due to lagging current. Q is negative when capacitive reactive power. i.e. due to leading current. The same concept is obtained when we consider $S=VI^*$ & not when considered $S=V*I$</p>	
b) Ans.	<p>List the advantages of PU system. Advantages of PU calculations:-</p> <ol style="list-style-type: none"> 1. Manufacturers specify impedance of apparatus in % or P.U. values on basis of name plate rating. 2. p.u. impedance of machine of same type having different ratings usually lay within narrow range though actual values differs with rating. Hence if impedance is not known, we can consider value from table in which avg. value for different type of machine are given. 3. P.u values are same referred to either side of transformer. 4. Type of connection of 3Φ transformer in 3Φ circuit does not affect p.u. values. 	<p>4M</p> <p><i>Any 4 each advantage 1M</i></p>	
c) Ans.	<p>What is transposition of 3 ϕ line? State its advantages. Transposition of conductors means exchanging the positions of the conductors at regular intervals along the line such that each conductor occupies the original position of every other conductor over equal distance.</p> <p>Unsymmetrical Spacing in the transmission line causes the flux linkages and therefore the inductance of each phase to be different resulting in unbalanced receiving end voltages even when sending end voltages and line currents are balanced. Also voltages will be induced in the adjacent communication lines when the line currents are balanced. This problem is reduced by transposition.</p>	<p>4M</p> <p>1M</p> <p>1M</p>	



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WINTER – 2016 EXAMINATION

Model Answer

Subject Code:

17510

	$B = Z = 180 \angle 75^\circ \Omega$ $C = Y \left(1 + \frac{YZ}{4} \right)$ $= 1 \times 10^{-3} \angle 90^\circ \left[1 + \frac{(1 \times 10^{-3} \angle 90^\circ)(180 \angle 75^\circ)}{4} \right]$ $= 1 \times 10^{-3} \angle 90^\circ \times 0.9566 \angle 0.697$ $= 9.566 \times 10^{-4} \angle 90.697 \text{ siemens}$	2M
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