

Subject Code: 17415 (DMT)

Important Instructions to examiners:

1) The answers should be examined by key words and not as word-to-word as given in the model answer scheme.

2) The model answer and the answer written by candidate may vary but the examiner should assess the understanding level of the candidate.

3) The language errors such as grammatical, spelling errors should not be given importance (Not applicable for subject English and Communication Skills).

4) While assessing figures, examiner may give credit for principal components indicated in the figure. The figures drawn by candidate and model answer may vary. The examiner should give credit for any equivalent figure/figures drawn.

5) Credits to be given step wise for numerical problems. In some cases, the assumed constant values may vary and there may be some difference in the candidate's answers and model answer (as long as the assumptions are not incorrect).

6) In case of some questions credit may be given by judgment on part of examiner of relevant answer based on candidate's understanding.

7) For programming language papers, credit may be given to any other program based on equivalent concept



| | Summer – 2017 Examinations Model Answer S | Subject Code: 17415 (DMT) |
|------|--|---|
| 1 | Attempt any <u>TEN</u> of the following: | 20 |
| 1 a) | State Fleming's right hand rule. Ans: Fleming's Right Hand Rule: Stretch out the first three fingers of your right hand such that the mutually perpendicular to each other , <i>align</i> first finger in direction magnetic field, thumb in direction of relative motion of conductor respect to field <i>then</i> the middle finger will indicate the direction EMF / current. | on of 2 Marks |
| 1b) | Give the two functions of yoke in DC motor. Ans: Functions of yoke in DC motor: Provides mechanical support for poles. Acts as protecting cover for machine. Provides path for magnetic flux. | 1 Mark for each function (any two) =2 Marks |
| 1 c) | State the principle of operation of a dc motor. Ans: Principle of operation of a dc motor: When a current carrying conductor is placed in a magnetic field conductor experiences the mechanical force. The magnitude of for given by F = BIL newton where $F - Force$, $B - Maximum$ flux density, $I - Current$, L - Active length of conductor | |
| 1 d) | Write voltage equation & power equation of DC motor. Ans: Voltage equation: 1) $V = E_B + I_A R_A$ (for DC shunt motor) V = applied voltage ,volts, $E_B =$ back emf generated (volts), $I_A =$ armature current (Amperes), $R_A =$ armature winding resistance in ohms. 2) $V = E_B + I_A(R_A + R_S)$ (for DC series motor) $R_S =$ series winding resistance in ohms | Any one voltage equation 1 Mark |
| | Power equation:1) $VI = E_B I_A + (I_A)^2 R_A + (I_{SH})^2 R_{SH}$ (for DC shunt motor) $V =$ applied voltage (volts), $I =$ current drawn by motor from supply (amperes), $E_B =$ back emf generated (volts), $I_A \& I_{SH} =$ armature & shunt field currents respectively (amperes), $R_A \& R_{SH} =$ armature & shunt field winding resistances respectively(ohms).2) $VI = E_B I + I^2 (R_A + R_S)$ (for DC series motor) $R_S =$ series winding resistance in ohms(some students may give the relevant equations for the compound m for which they should be awarded marks) | Any one power equation 1 Mark |



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| 1e) | How will you change the direction of rotation of a d.c.motor? Ans: | 1 Mark for |
| | (i) By reversing direction of only Armature current. (ii) By reversing the direction of only field current. | each method = 2 Marks |
| 1 f) | A dc motor operating on a supply voltage of 200V dc has a resistance of 0.5Ω . If armature current is 25A, Calculate the back | |
| | Ans: $E_b = V - I_a R_a$ $= 200 - 25 \times 0.5$ | 1Mark |
| 1 \ | = 187.5 volts | 1Mark |
| 1g) | Define: i) Transformation Ratio ii) Turns Ratio related to 1-φ transfor Ans: i) Transformation Ratio: | rmer. |
| | It is defined as ratio of secondary voltage to primary voltage or secondary turns to primary turns or primary current to secondary ii)Turns Ratio: | |
| | It is defined as ratio of secondary turns to primary turns or primar to secondary turns. | 1Mark |
| 1h) | State working principle of a transformer. Ans: Working principle of a transformer: The transformer operates on the principle of mutual induction. When ac supply is applied to primary it circulates ac flux in corrising principle of link with secondary. The changing linking flusecondary produces emf in secondary. | |
| 1 i) | Name the two components of no load current I_o of 1- ϕ transformer also write down their formulae. | er and |
| | Ans: i) Active or working or iron loss component $I_w = I_0 \cos \phi_0$ | 1Mark |
| | i) Magnetizing component $I_{\mu} = I_{o} \sin \phi_{0}$ | 1Mark |
| 1 j) | State the condition for maximum efficiency for single phase trans Ans: Condition for maximum efficiency for single phase transform Iron loss = Copper loss OR Constant loss = Variable loss | |
| 1k) | State any two advantage of three phase transformer over a bank o single phase transformer. Ans: | |
| | Advantages of three phase transformer over bank of single p transformers: | hase |
| | For identical magnitudes of power transformation,i) Saving in copper conductor. | 1 Mark for |

Summer – 2017 Examinations **Model Answer** Subject Code: 17415 (DMT) ii) Saving in electromagnetic core material. each (any Compact arrangement (Lower space required) iii) two) Saving in dielectric material such as insulating oil. = 2 Marks iv) Saving in overall cost. v) Higher efficiency. vi) Give any two advantages of star-star connection in 3-¢ transformers. Ans: Advantages of star-star connection in 3-¢ transformers: 1. It is possible to use the transformer for 3-phase, four wire system 1Mark for because of neutral. each of any 2. The phase shift between primary and secondary emfs is zero. two 3. As phase current equal line current, windings have to carry large advantages currents; hence can be used for supplying large load currents. 4. As phase voltage is $1/\sqrt{3}$ times line voltage, the no.of turns required for primary and secondary are less, hence economical. Attempt any <u>FOUR</u> of the following: 16 Distinguish between lap and wave winding. (Any four points). Ans:

Wave winding

No. of parallel paths(A) is

Current in each conductor

Coil travels in the form of

wave hence name is wave

Dummy coil may be

equal to two(2).

 $= I_a/2$

winding.

required.

No. of brushes = 2.

| | | | requireu. |
|----|---|------------------------------------|-----------------------------------|
| | 6 | Resultant pitch $Y_R = Y_B - Y_F$ | Resultant pitch $Y_R = Y_B + Y_F$ |
| | | (Difference of Y_B and Y_F) | (Sum of Y_B and Y_F) |
| | 7 | Y_C (Commutator pitch) = ± 1 | Y_C (Commutator pitch) = |
| | | | $Y_R/2$ |
| | 8 | Used for high current, low | Used for low current, high |
| | | voltage applications | voltage applications |
| b) | | | |

Ø7NP

Ans:

2

$$E_{g} = \frac{\varphi ZW}{60A}$$
$$\therefore \phi = \frac{E_{g} \times 60A}{ZNP} = \frac{240 \times 60 \times 6}{1080 \times 500 \times 6} = 0.02667 Wb$$

Lap winding

No. of brushes = No. of poles

Current in each conductor =

Coil overlaps hence name is

Dummy coil is not required.

No. of parallel paths(A) is

equal to No. of poles(P).

2c) Draw the circuit diagram of

Stepwise solution 4 Marks

each of any four points

1 Mark for



11)

2

2a)

Sr.

No.

1

2

3

4

5

 I_a/A

lap winding.



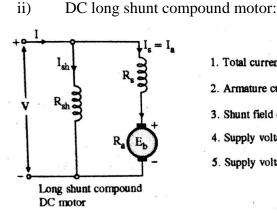
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- i) DC series motor.
- ii) DC long shuntcompound motor. Also write down the related equation.

Ans:
i) DC series motor:
I. Total cu
R, 2. Supply
J. Flux
$$\phi$$

4. This is p

1 Mark for
each1. Total current $\mathbf{l} = \mathbf{l}_{\mathbf{s}} = \mathbf{l}_{\mathbf{a}}$ 2. Supply voltage $\mathbf{V} = \mathbf{E}_{\mathbf{b}} + \mathbf{l}_{\mathbf{a}}(\mathbf{R}_{\mathbf{a}} + \mathbf{R}_{\mathbf{s}}) + \mathbf{V}_{brush}$ 3. Flux $\phi \propto \mathbf{l}_{\mathbf{a}}$ or $\mathbf{l}_{\mathbf{s}}$ 4. This is not a constant flux motor5. Armature voltage $= \mathbf{E}_{\mathbf{b}} + \mathbf{I}_{\mathbf{a}} \mathbf{R}_{\mathbf{s}} + \mathbf{V}_{brush}$



- Total current I = I_{sh} + I_s = I_{sh} + I_a
 Armature current I_a = I_s
 Shunt field current I_{sh} = V/R_{sh}
 Supply voltage V = I_{sh}R_{sh}
 Supply voltage V = E_s + I (R + R) + V
- 5. Supply voltage $V = E_b + I_a(R_a + R_s) + V_{brush}$
- 2d) What is back emf in DC motor? Explain its significance. Ans:

Back emf:

When the armature of DC motor rotates under the fixed magnetic field and cuts it, by Faradays law an emf is induced in them. The induced emf acts in opposite direction to the applied voltage as per Lenz's law. Hence known as back or counter emf E_{b} .

Significance of back emf:

Armature current,
$$I_a = \frac{V - E_b}{R_a}$$

- i) If the motor is at standstill or rest E_b is zero. This causes large current flow through armature, which produce high starting torque.
- ii) When motor takes speed, the back emf increases, causes armature current to decrease hence decrease in torque.
- iii) It follows therefore that back emf in DC motor regulates the flow of armature current i.e. it automatically changes the armature current to meet load requirements.
- 2e) Draw and explain the following characteristics in DC shunt motor:
 - i) Torque vs Armature current.

1 Mark

1 Mark

Significance

2 Marks



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ii) Speed vs Torque.

| • | | ~ | |
|---|---|---|--|
| A | п | s | |
| | | | |

| Torque Vs Armature current | Speed Vs Torque | 1Mark for |
|--|--|----------------------------------|
| Torque T Armature current I _A | (S) Paads S Torque (T) | each characterist ic |
| $T_a \propto \phi . I_a$ Field current is constant Flux is also constant Therefore $T_a \propto I_a$ Hence the characteristic is straight line passing through zero. | $N \propto \frac{E_b}{\emptyset}$ The flux and back emf E_b are almost constant, hence the speed of shunt motor almost remains constant; however the speed drops with increase in load torque. | 1Mark for each explanation |

2f) A 500V DC shunt motor takes a current of 5amp on no load. The resistances of the armature and field circuits are 0.5Ω and 250Ω . Calculate the efficiency when the motor takes a current of 100amp. **Ans:**

No load Motor Input $P_{in} = v \times I_{L0} = 500 \times 5 = 2500W$ Shunt field current $I_{sh} = \frac{v}{R_{sh}} = \frac{500}{250} = 2A$ 1 Mark No load armature current $I_{a0} = I_{L1} - I_{sh} = 5 - 2 = 3A$ No load armature Cu loss $(P_{cu0}) = I_{a0}^2 \times R_a = 3^2 \times 0.5 = 4.5W$ Field Cu loss = field voltage × field current $= 500 \times 2 = 1000W$ $P_{constant} = No \ load \ Motor \ Input - No \ load \ armature \ Cu \ loss$ - Field Cu loss 1 Mark $P_{constant} = 2500 - 4.5 - 1000 = 1495.5W$ Full load armature current $I_{a1} = I_{L1} - I_{sh} = 100 - 2 = 98A$ Full load armature Cu loss(P_{cu1}) = $I_{a1}^2 \times R_a = 98^2 \times 0.5$ = 4802 WTotal full load losses = armature Cu loss + fieldCu loss + constant loss *Total full load losses* = 4802 + 1000 + 1495.5 = 7297.5*W* 1 Mark *Full load input power = input voltage × current drawn by motor* $P_{IFL} = 500 \times 100 = 50000W$

:. Full-load efficiency is given by, $\% \eta_{FL} = \frac{motor \ input - losses}{motor \ input} \times 100$



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1 Mark

16

$$\% \eta_{FL} = \frac{50000 - 7297.5}{50000} \times 100 = 85.4\%$$

3 Attempt any <u>FOUR</u> of the following:

- 3a) With the help of neat diagrams, explain the following methods of speed control in DC series motor.
 - i) Field diverter method.
 - ii) Armature diverter method.

Ans:

(i) Field diverter method:

- Resistance connected in parallel with field winding

-By adjusting this resistance current can by diverted from field winding

-Thus field current decreases and the speed can be increased above rated speed.

(ii) Armature diverter method:

-Resistance is connected in parallel with armature winding.

-This diverter resistance shunts some of the line current, thus reducing armature current.

-Now for a given load if armature current decreased, the flux must increase and hence speed is decreased than the rated speed.

3b) Give the classification of transformer based on:

- i) Construction
- ii) Voltage level
- iii) Number of phases
- iv) Applications

Ans:

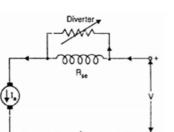
Classification of transformer based on:

- i) Construction:
- Shell type, Core type, Berry type ii) Voltage level:
- Step-Up, Step-Down,
- iii) Number of phases:
 - Single phase, Three phase
- iv) Applications:
 - Power T/F, Distribution T/F
- 3c) Compare core type and shell type transformer on any four parameters.

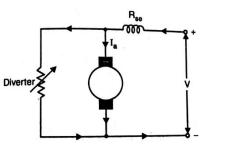
Ans:

Comparision of core type and shell type transformer:

| | | |
|---------|-----------|------------|
| Sr. No. | Core type | Shell type |



2Marks



2 Marks

1 Mark for each classificatio n = 4Marks



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| 1 | | |
|----|---|---|
| 2 | It has one window | It has two windows |
| 3 | It has one magnetic circuit. | It has two magnetic circuits. |
| 4 | Core surrounds the winding. | Winding surrounds the core |
| 5 | Average length of core is more. | Average length of core is less. |
| 6 | Area of cross section is less so more turns are required. | Area of cross section is more so less turns are required. |
| 7 | Better cooling for winding | Better cooling for core |
| 8 | Mechnical strength is less | Mechnical strength is high |
| 9 | Repair and maintenance is easy | Repair and maintenance is difficult |
| 10 | Application: Low current, high voltage | Application: High current, low voltage |

1 Mark Each for any four differences = 4 marks

3d) Derive the emf equation of a transformer. Ans:

Emf equation of transformer:

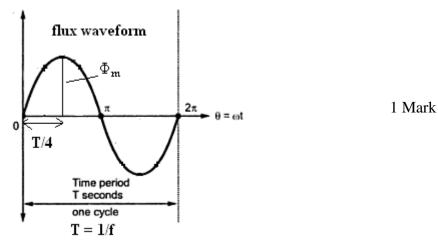
 $N_1 = No.$ of turns on primary winding

 $N_2 = No.$ of turns on secondary winding

 Φ_m = maximum value of flux linking both the winding in Wb

F = Frequency of supply in Hz

1st method



Maximum value of flux is reached in time t = 1/4fAvg. rate of change of flux $=\Phi_m/t = \Phi_m/(1/4f) = 4\Phi_m f$ Wb/sec From faraday's laws of electromagnetic induction 1 Mark



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| Avg. emf induced in each turn = Avg. rate of change of flux = $4\Phi_m f$ | 1 Mark |
| Form factor = (RMS value)/(Avg. value) = 1.11 | |
| R.M.S. emf induced in each turn = 1.11 x Avg. value = 1.11 x $4\Phi_{m}f$ | 1 Mark |
| $=$ 4.44 Φ m f volts | |
| R.M.S. emf induced in primary winding = (RMS emf / turn) x | |
| \mathbf{N}_1 | |
| $E_1 = 4.44 \Phi_m f N_1$ volts | |
| Similarly, $E_2 = 4.44 \Phi_m f N_2$ volts | |
| OR 2 nd method | |
| $\Phi = \Phi_{\rm m} \sin \omega t$ | |
| According to Faraday's laws of electromagnetic induction | |
| Instantaneous value of emf/ turn = - $d\Phi/dt$ = -d /dt ($\Phi_m \sin \omega t$) | |
| $= -\omega \Phi_{\rm m} \cos \omega t$ | 1 Mark |
| $= \omega \Phi_{\rm m} \sin(\omega t - \pi/2)$ volts | |
| Maximum value of emf/turn= $\omega \Phi_m$ | 1 Mark |
| But $\omega = 2\pi f$ | |
| Max. value of emf/turn = $2\pi f \Phi_m$ | |
| RMS value of emf/turn = 0.707 x $2\pi f \Phi_m$ = 4.44 $\Phi_m f$ volts | 1 Mark |
| RMS value of emf in primary winding $E_1 = 4.44 \Phi_m f N_1$ volts $E_2 = 4.44 \Phi_m f N_2$ volts | 1 Mark |
| Draw the connection diagram of Delta-star connection of $3-\phi$ Transformer and give any two advantages and disadvantages of this connection. Ans: | |
| Connection diagram of Delta-star connected 3-¢ Transformer: | |

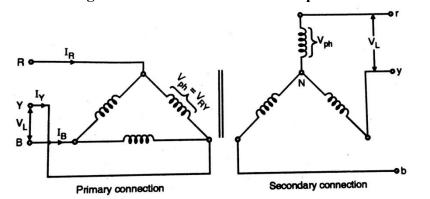


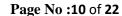
Diagram 2 Marks

Advantages:

3e)

- i) As primary is connected in delta, distortion due to third harmonic is absent.
- ii) Phase shift of 30° electrical is present between the primary and secondary line voltages and line currents.

Two Advantages 1 Mark



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| iii) | Small cross section wire can be used on primary side due to | |
|---|---|----------------------|
| iv) | delta connection. Due to availability of neutral on the secondary side, it is | |
| Dica | possible to use it for 3ph 4wire system. dvantages: | |
| i) | In this type of connection, the secondary voltage is not in phase with the primary. Hence it is not possible to operate this connection in parallel with star-star or delta-delta connected | Two Dis- |
| ii) | transformer. One problem associated with this connection is that the secondary voltage is shifted by 30^0 with respect to the primary voltage. This can cause problems when paralleling 3-phase transformers since transformers secondary voltages must be in-phase to be paralleled. Therefore, we must pay attention to these shifts. | advantages 1 Mark |
| iii) | If secondary of this transformer should be paralleled with secondary of another transformer without phase shift, there would be a problem. | |
| iv) | As line current is equal to phase current the conductor size of winding should be large. | |
| maximum sectional primary Ans: Cross sec | 230V, 50Hz single phase transformer is to be operated at a m flux density of $1.2Wb/m^2$ in the core. The effective cross area of the transformer is $150cm^2$. Calculate suitable values of and secondary turns. ctional Area, A=150cm ² = $150 \times 10^{-4} m^2$ cy f=50Hz, Max. flux density B _m = $1.2wb/m^2$ | |
| As $\Phi_m =$ To find I | $B_m \times A = 1.2 \times 150 \times 10^{-4} = 0.018$ Wb. | 1 Mark |
| | $\Phi_{\rm m} f {\rm N}_1$ volt | |
| 3300 = 4 N ₁ = 826 | $44 \times 0.018 \times 50 \times N_1$ 5 turns | 2Mark |
| | $N_2 = \frac{E_2}{E_1} \times N_1 = \frac{230}{3300} \times 826 = 58 \text{ turns}$ | 1 Mark |
| Attempt | any <u>FOUR</u> of the following: | 16 |
| 5A at 0.2 | ransformer with a ratio of 440/110 V takes a no load current of 2pf lagging. If the secondary supplies a current of 120Amp at a lagging, estimate the current taken by the primary. | |
| $\frac{\mathrm{V}_2}{\mathrm{V}_1} = \frac{\mathrm{N}_2}{\mathrm{N}_1}$ | $=\frac{110}{440}=0.25$ | 1Mark |
| | | |

 $I_0 = 5A$, $\cos\Phi_0 = 0.2$ hence $\sin\Phi_0 = 0.98\Phi_0 = 78.463^0$



3f)

4

4 a)



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| | $I_2 = 120A$, cos $\Phi_2 = 0.8$ hence sin $\Phi_2 = 0.6\Phi_2 = 36.86^0$ | 1 Mark |
| | Therefore for load component I'1 of primary current corresponding | to I ₂ , |
| | $I'_1N_1{=}I_2N_2$, i.e. $I'_1{=}k\times I_2{=}0.25\times 120{=}30A$ | 1 Mark |
| | Using law of parallelogram; $I_1^2 = I'_1^2 + I_0^2 + 2 \times I'_1 \times I_0 \times \cos(\Phi_0 - \Phi_2)$ $= (30)^2 + (5)^2 + [(2 \times 30 \times 5) \times \cos(78.46 - 36.86)]$ $I_1 = 33.9A$ | 1 Mark |
| | OR any equivalent method to find I_1 | |
| 4 b) | A 50KVA, 4400/220V transformer has R₁=3.45Ω, R₂=0.009Ω. The value of reactances are X₁=5.2Ω, X₂=0.015Ω. Calculate for the transformer: i) Equivalent resistance and reactance as referred to HV side. ii) Equivalent resistance and reactance as referred to LV side. | |
| | Ans: | |
| | Equivalent resistance and reactance as referred to HV side: | |
| | $k = \frac{220}{4400} = 0.05$ | |
| | | |
| | $R'_{2} = \frac{R_{2}}{K^{2}} = \frac{0.009}{(0.005)^{2}} = 3.6\Omega$ | |
| | | 1 Mark |
| | $X_2' = \frac{X_2}{K^2} = \frac{0.015}{(0.005)^2} = 6\Omega$ | |
| | $R_{1T} = R_1 + R_2' = 3.45 + 3.6 = 7.05 \Omega$ | |
| | $X_{1T} = X_1 + X_2' = 5.2 + 6 = 11.2 \Omega$ | 1 Mark |
| | Equivalent resistance and reactance as referred to LV side: | |
| | $R'_1 = R_1 \times k^2 = 3.45 \times (0.05)^2 = 8.625 \times 10^{-3} \Omega$ | 1 Mark |
| | $X'_1 = X_1 \times k^2 = 5.2 \times (0.05)^2 = 0.013 \Omega$ | |
| | $R_{2T} = R_{21} + R'_1 = 0.009 + 8.625 \times 10^{-3} = 0.0176$ | δΩ |
| | $X_{2T} = X_2 + X_1' = 0.015 + 0.013 = 0.028 \Omega$ | 1 Mark |
| 4 c) | Efficiency of 400kVA, 1-Φ Transformer is 98.77%, when delivering load at 0.8pf and it is 99.13% at half load unity pf. Calculate: i) Iron loss | g full |
| | ii) Full load copper loss. | |
| | Ans: $KVA \times 1000 \times PF$ | |
| | Full load effciency, $\eta_{FL} = \frac{KVA \times 1000 \times PF}{(KVA \times 1000 \times PF) + P_i + P_{cu}} \times 1^{-1}$ | 00 |
| | $P_i = Iron \ loss \ which \ is \ constant.$ | |
| | $P_{cu} = Full \ load \ Cu \ loss$ | |
| | $\therefore 0.9877 = \frac{400 \times 1000 \times 0.8}{(400 \times 1000 \times 0.8) + P_i + P_{cuFL}} = \frac{320000}{320000 + P_i + P_{cuFL}}$ | |
| | $(400\times1000\times0.01\pm1)\pm12$ and $520000\pm12\pm12$ and 51 | |
| | $\therefore P_i + P_{cuFL} = 3985W \dots \dots \dots \dots \dots (i)$ | 1 Mark |



4 d)

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$$\begin{aligned} P_{cuHL} &= \frac{1^2}{2} \times P_{cuFL} = \frac{P_{cuFL}}{4} \\ Efficiency at Half load, \eta_{HL} \\ &= \frac{1/2 \times KVA \times 1000 \times PF}{(1/2 \times KVA \times 1000 \times PF) + P_l + P_{cuHL/4}} \\ &= \frac{1/2 \times 400 \times 1000 \times 1}{(1/2 \times 400 \times 1000 \times 1) + P_l + \frac{P_{cuFL}}{4}} \\ P_l + \frac{P_{cuFL}}{4} &= 1755.27W \dots (il) \\ \text{Subtracting (ii) from (i) and solving we get,} \\ P_{cuFL} &= 2973 W \text{ and} \\ P_l &= 1012W \\ \text{Two } l - \phi \text{ transformers with equal turns ratio have impedance of } (0.5+j3) \\ \Omega \text{ and } (0.6+j10) \Omega \text{ with respect to secondary. If they are operated in parallel, determine how they will share a total load of 100kW at pf 0.8 \\ lagging. \\ \textbf{Ans:} \\ Z_A &= (0.5 + j3) = 3.04 < 80.6^0 \\ Z_B &= (0.6 + j10) = 10.02 < 86.6^0 \\ Z_A + Z_B &= (1.1 + j13) = 13.05 < 85.2^0 \\ \therefore kVA &= \frac{kW}{pf} = \frac{100}{0.8} = 125kVA, i. e.S = 125 < -36.9^0 kVA \\ \text{S}_A &= S \times \frac{Z_B}{Z_A + Z_B} = 125 < -36.9^0 \times \frac{10.02 \times 86.6^0}{13.05 \times 85.2^0} \\ \text{I Mark} \\ \therefore \text{ Load shared by Transformer A in kW will be;} \\ kVA \times pf &= 95.97 \times \cos(-35.5^0) = 78.2kW \end{aligned}$$

$$S_B = S \times \frac{Z_A}{Z_A + Z_B} = 125 < -36.9^{\circ} \times \frac{3.04 < 80.6^{\circ}}{13.05 \times 85.2^{\circ}} = 29.11 < -41.5^{\circ}$$

$$\therefore \text{ Load shared by Transformer B in kW will be;} kVA \times pf = 29.11 \times \cos(-41.5^{\circ}) = 21.8kW$$

4 e) Draw a neat experimental set up to conduct OC test on a single phase transformer. Also give reason why it is preferable to conduct OC test on LV side?
 Ans:

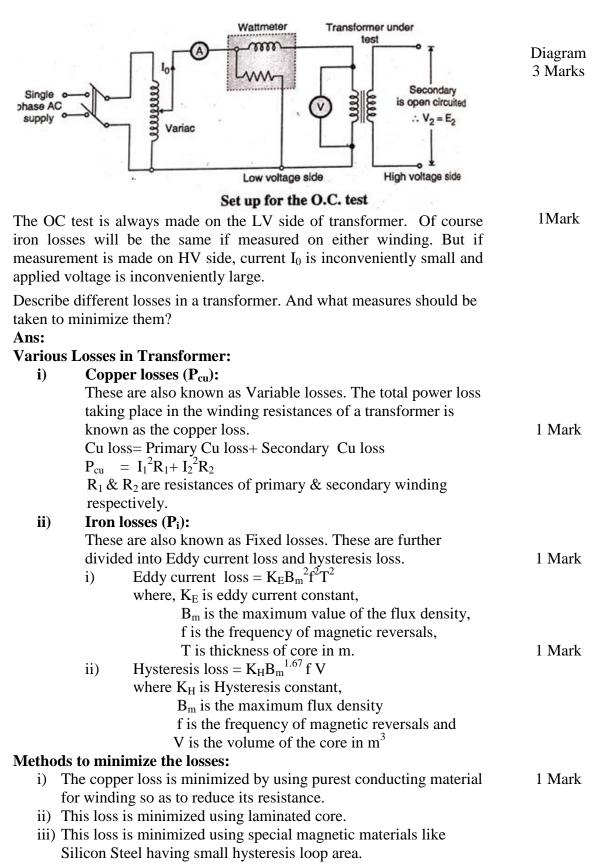
Experimental set up to conduct OC test:



4f)

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5 Attempt any <u>FOUR</u> of the following

16



5a)

5b)

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|---|--------------------------|
| Give any two advantages of parallel operation and any two conditions be satisfied for parallel operation of $1-\Phi$ transformers. | ns to |
| Ans: | |
| Advantages of parallel operation of transformers: | A my true |
| Reliability of the supply system enhances. Highly varying load demands can be fulfilled | Any two adv |
| ii) Highly varying load demands can be fulfilled.iii) Loading only the relevant capacity transformer to operate a | |
| high efficiency. | each= |
| iv) Overloading of transformers is avoided and hence of life of | 2 Marks |
| transformer increases. | 2 Warks |
| (Any related advantages should be considered) | |
| Conditions for Parallel operation of 1 phase transformer: | Any two |
| 1) Voltage ratings of both the transformers must be identical. | conditions |
| 2) Percentage / p.u. impedances should be equal in magnitude. | 1 mark |
| 3) X/R ratio of the transformer windings should be equal. | each= |
| 4) Transformer polarity wise connections must be carried out. | 2 Marks |
| A 1 phase 50kVA, 2400/120V, 50Hz transformer gave following terresults:- OC Test(Instruments on LV side): 120V, 9.85A, 396W SC Test(Instruments on HV side): 92V, 20.8A, 810W Calculate: i) The equivalent circuit constants ii) Efficiency at rated kVA and 0.8pf lagging. Ans: To find R ₀ and X ₀ from OC test; $cos \phi_0 = \frac{W_0}{V_2 \times I_0} = \frac{396}{120 \times 9.85} = 0.335$ Hence $\phi_0 = 70.42^0$ $R_0 = \frac{V_2}{I_0 \times cos \phi_0} = \frac{120}{9.85 \times 0.335} = 36.366\Omega$ $X_0 = \frac{V_2}{I_0 \times sin \phi_0} = \frac{120}{9.85 \times 0.9422} = 12.93\Omega$ | st 1Mark |
| To find \mathbf{R}_{1T} , \mathbf{X}_{1T} and \mathbf{Z}_{1T} from SC test; $R_{1T} = \frac{W_{sc}}{I_{sc}^2} = \frac{810}{20.8^2} = 1.872\Omega$ $Z_{1T} = \frac{V_{sc}}{I_{sc}} = \frac{92}{20.8} = 4.423\Omega$ | 2 Marks |
| $X_{1T} = \sqrt{Z_{1T}^2 - R_{1T}^2} = \sqrt{4.423^2 - 1.872^2} = \sqrt{16.0585} = 4.0073\Omega$ To find efficiency; $P_i = 396W$ $P_{cu} = 810W$ Efficiency at full load; $\eta_{FL} = \frac{V \times I \times \cos \phi_0}{V \times I \times \cos \phi_0 + P_i + P_{cu}} \times 100$ | |



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$$=\frac{50\times10^3\times0.8}{50\times10^3\times0.8+396+810}\times100$$

= **97**.**07**%

5c) Find all day efficiency of 500kVA distribution transformer whose copper and iron losses at full load are 405kW and 3kW. It is loaded as under per day:

| No. of hours | 6 | 6 | 8 | 4 | |
|-------------------|------------------------------|---------------------------------|--------------------------|--------------------------------|---------------------------|
| Load in kW | 450 | 300 | 150 | 0 | |
| Power factor | 0.9 | 0.75 | 1 | - | |
| Ans: | | | | | |
| Step I: Convert | the loading f | from kW to k | VA | | |
| i) The loading of | | 1 1 | • | , | 1 Marl |
| ii)The loading of | f 300 kW at 0 | 75 pf is equiv | alent to $(300/0)$ | (0.75) = 400 | |
| kVA | | | | | |
| iii)The loading o | | | | | |
| Step II: Caclula | | | | | 1 . 4 . 1 |
| | Cu loss i.e. fo | or 500 kVA= 4 | 4.5kW is giver | n which is for 6 | 5 1 Marl |
| hours. | | | | | |
| | | | 2.88kW is for | | |
| , | ` | $(00)^2 \times 4.5 \text{kW} =$ | 0.405kW is fo | or 8 hours | |
| iv) No Load | | | | | |
| Total Energy los | | | 47 50 1 33/1 | | |
| 、 | , , | $(6)+(0.405 \times 8)$ | | | |
| Step III:Calcula | | 0. | | | |
| | | due to iron lo | SS 111 24111S | | 1 Mar |
| - | x 24 = 72 kWl t Enorgy | 1 | | | 1 Wian |
| Step IV:Output | | x6) + (150x8) | – 5700 kWh | | |
| $L_{out} - (4)$ | +30x0) + (300) | (130x0) + (130x0) | - 3700 K W II | | |
| | . 0 | utput Energ | y in 24 hrs of | f a day | |
| All – day effic | ciency $\eta = \frac{1}{Ir}$ | mut enerav | in 24 hrs of t | $\frac{1}{he dav} \times 100$ |) |
| | | | in 24 hrs of a | | |
| = [Output energy] | | | | ron loss] in 24 | $\overline{\overline{4}}$ |
| × 100 | | 1 | 1 | - | |
| | | 5700 | | | |
| | $=\frac{1}{5700}$ | 5700 + 47.52 + 72 | $\frac{1}{2} \times 100$ | | |
| | Lo. 00 | | T | | 1 Marl |

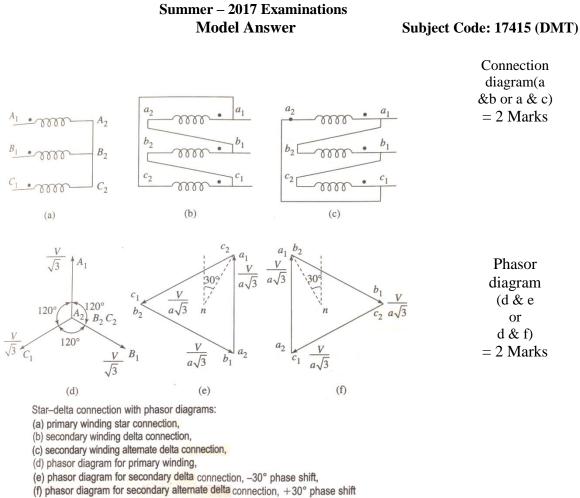
All day efficiency η =97.946 %

5d) Draw the connection diagram and phasor diagram of star-delta connection used for 3 phase transformer connection. **Ans:**

1Mark

1 Mark





The terminals can be marked as R₁, R₂ for R-phase and so on for HV terminals and r_1 - r_2 for R-phase and so on for LV terminals.



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5e) Compare Power and Distribution Transformer on the following parameters:
i)Typical voltages ii) Power Ratings iii)Size
iv)Load
v)Insulation level
vi)Installation
vii)Maximum efficiency
viii)Type of efficiency
Ans:-

| Parameters | Power Transformer | Distribution |
|-----------------|---------------------------|--------------------------|
| | | Transformer |
| i)Typical | 400kV, 220kV, | 11kV,6.6kV, 3.3kV, |
| Voltages | 110kV,66kV,33kV | 440V, 230V |
| ii)Power | Higher (> 1MVA) | Lower (< 1MVA) |
| Rating | | |
| iii)Size | Big | Small |
| iv)Load | Full load | 50-70% of full load |
| v)Insulation | High | Low |
| Level | | |
| vi)Installation | Being large capacity | Being small capacity |
| | installation is difficult | installation is easy and |
| | and generally in | generally in public |
| | consumer's premises. | place. |
| vii)Maximum | Obtained near 100% | Obtained near 50% of |
| efficiency | of full load | full load |
| viii)Type of | Only power | All day efficiency needs |
| efficiency | efficiency is sufficient | to be defined |

 $\frac{1}{2}$ mark each = 4Marks



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5 f) With the help of neat diagram, explain the procedure of phasing out test on 3 phase transformer.

Ans:-

-Short primary & secondary winding of other phases expect the one under test.

-Connect voltmeter to secondary winding.

-A small DC current is circulated through the primary winding through switch.

-Now with the help of switch interrupt

the DC supply instantly & repeatedly.

-If voltmeter indicator deflects than it indicates the two windings concerned belong to the same phase.

-If not deflect then two windings are

not belong to same phase.

-Repeat the procedure by connecting

voltmeter to secondary side to next secondary winding till voltmeter gives deflection.

-In this way we can search the phasing out.

OR

-This test is carried to find out the corresponding HV and LV phase winding.

-The circuit diagram is as shown in figure. Here normal ac voltage is applied to one of the HV or LV windings. In this case to HV winding and the voltages across all three LV windings are measured.

-The winding across which is

much more compared to other two windings represents the secondary of the winding to which supply is connected.

L

IN

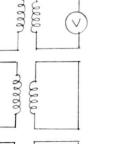
-The test repeated for finding out remaining concerned secondary windings in the same manner.

6 Attempt any <u>FOUR</u> of the following

6a) Describe the construction and operation of three phase autotransformer with the help of neat diagram.

Ans:

Construction and operation of three phase autotransformer:



Iph Ac

-ann

Explanation 2 Marks

Diagram

2 Marks

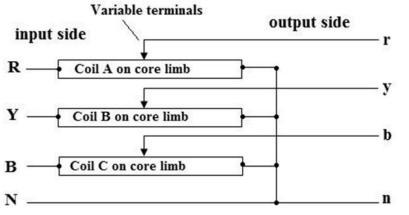
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Diagram 1



Subject Code: 17415 (DMT)

Mark



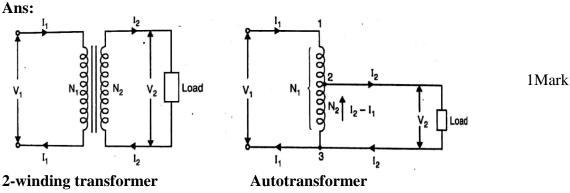
Construction:

- The coils connected in star are placed on electromagnetic cores, each phase of auto-transformer consists of a single continuous winding common to primary and secondary circuit.
- The limbs (electromagnetic cores) are made of laminations (sheet steel with Silicon).
- The output terminal connections are gang operated to get identical tapings on all phases and are brought out on the insulated plate. The variable voltage may also be obtained by tapings (stepped voltage instead of smooth variations) to which the output terminals are connected as required.

Operation:

- Working principle is based on self-induction.
- When three-phase ac supply is given to star connected three windings, flux is produced and gets linked with each phase winding. The emf is induced in it according to self-induction.
- As only one winding per phase is available, part of it acts as secondary between variable terminal and neutral.
- Depending upon the position of variable terminal, we get variable AC voltage at the output.

6b) Illustrate the saving in copper by using $1-\Phi$ auto transformer instead of two winding transformer of the same rating by deriving proper expressions.



1 Mark

2 Mark

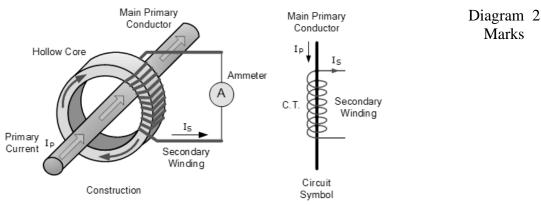


| Summer – 2017 Examinations | |
|--|---------------------------|
| Model Answer | Subject Code: 17415 (DMT) |
| i)Two winding transformer | |
| Weight of Cu required α (I ₁ N ₁ + I ₂ N ₂) | 1Mark |
| ii)Autotransformer | |
| Weight of Cu required in section 1-2 α I ₁ (N ₁ -N ₂) | |
| Weight of Cu required in section 2-3 α (I ₂ -I ₁)N ₂ | |
| \therefore Total weight of Cu required α I ₁ (N ₁ -N ₂)+ (I ₂ -I ₁)N ₂ | |
| Weight of Cu in autotransformer $I_1(N_1 - N_2) + (I_2 - I_1)$ |)N ₂ 1Mark |
| $\frac{\text{Weight of Cu in autotransformer}}{\text{Weight of Cu in ordinary transformer}} = \frac{I_1(N_1 - N_2) + (I_2 - I_1)}{(I_1N_1 + I_2N_2)}$ $= \frac{I_1N_1 + I_2N_2 - N_2I_1 - I_2}{(I_1N_1 + I_2N_2)}$ | N_2I_1 |
| Solving this we get, | 1Mark |
| $\frac{\text{Weight of Cu in autotransformer}}{\text{Weight of Cu in ordinary transformer}} = 1 - \frac{N_2}{N_1} = 1 - K$ | Tiviuix |
| | |
| :. Weight of Cu in autotransformer(W_a) = | |
| $\left[(1 - K) \left(\text{Weight of Cu in ordinary transformer}(W_o) \right) \right]$ | |
| $\therefore \text{Saving in } Cu = (W_o - W_a) = W_o - (1 - K)W_o = K W_o$ | |

6c) With the help of neat diagram, explain the construction of current transformer.

Ans:

Construction of current transformer:



- C.T. has bar type conductor, which behaves as primary winding.
- The primary of C.T. carries large current I_p which is to be measured, so the bar is of large cross sectional area.
- The secondary of C.T.is made up of large number of turns. It is wound on core. The secondary winding is a low current winding. Hence its cross sectional area is small. An ammeter of small range is connected across the secondary as shown in figure.
- 6d) Draw schematic diagram of welding transformer showing constructional features of a welding transformer. Also explain its working.Ans:

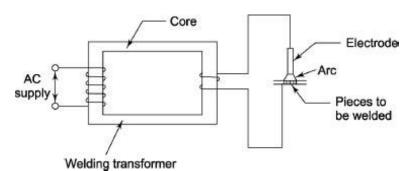
Constructional features of welding transformer:

Construction 2 Marks

2Marks



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Working of welding transformer:

i) It is a step down transformer that reduces the voltage from the source voltage to a voltage desired according to the demands of the welding process.

ii) Winding used is highly reactive or a separate reactor winding is added in series with the secondary winding.

iii) Having large & thin primary turns and low number but thick secondary turns.

iv) The secondary current is quite high. One end of secondary is connected to welding electrode while other end to the pieces to be welded.

v) Due to the contact resistance 'R' between the electrode and pieces to be welded a very high current flows creating high heat by I^2R that melts the tip of the electrode. The melted tip flows / fills the gap between the pieces to be welded creating a solid weld on cooling.

vi) The secondary has several taps for adjusting the secondary voltage to control the welding current.

vii) The transformer is normally large in size compared to other step down transformers as the windings are of a much larger gauge. vi) Common ratings:

> Primary voltage – 230 V, 415 V Secondary voltage – 40 to 60 V Secondary current – 200 to 600 A

working 2Marks



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6e) What is an isolation transformer? State any two applications of isolation transformer.

Ans:

- i) Isolation transformers are specially designed transformers for providing electrical isolation between primary & secondary windings. The transformer has primary and secondary windings placed on the common core limbs which have equal number of turns so that the voltage fed to the primary is available at the secondary without any change in its magnitude.
- ii) These are built with special insulation between primary and 2 Marks secondary.
- iii) The construction & working of isolation transformer is same as conventional transformers.

| Applications of isolation transformer: | Two |
|--|--------------------------|
| i) Disconnect the load equipment from supply ground: | application |
| ii) Reduction of voltage spikesiii) It acts as a decoupling device. | 1 Mark each= 2Mark |

6f) Draw a neat connection diagram of potential transformer. Also explain the two types of error that are likely to occur in the P.T. **Ans:**

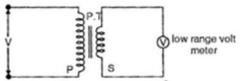


Diagram 2 mark

Errors occur in P.T.:

i) Voltage Ratio Error – The voltage ratio error is expressed in regarding measured voltage, and it is given by the formula as shown below.

Two errors 1 mark each= 2 Marks

Ratio Error = $\frac{K_t I_s - I_p}{I_p}$

where, K_t is the nominal ratio, i.e., the ratio of the rated primary voltage and the rated secondary voltage.

ii) **Phase Angle Error** – The phase angle error is the error between the secondary terminal voltage which is exactly in phase opposition with the primary terminal voltage. The increases in the number of instruments in the relay connected to the secondary of the potential transformer will increase the errors in the potential transformers.